

Unsupervised Learning of Visual Structure Using Predictive Generative Networks

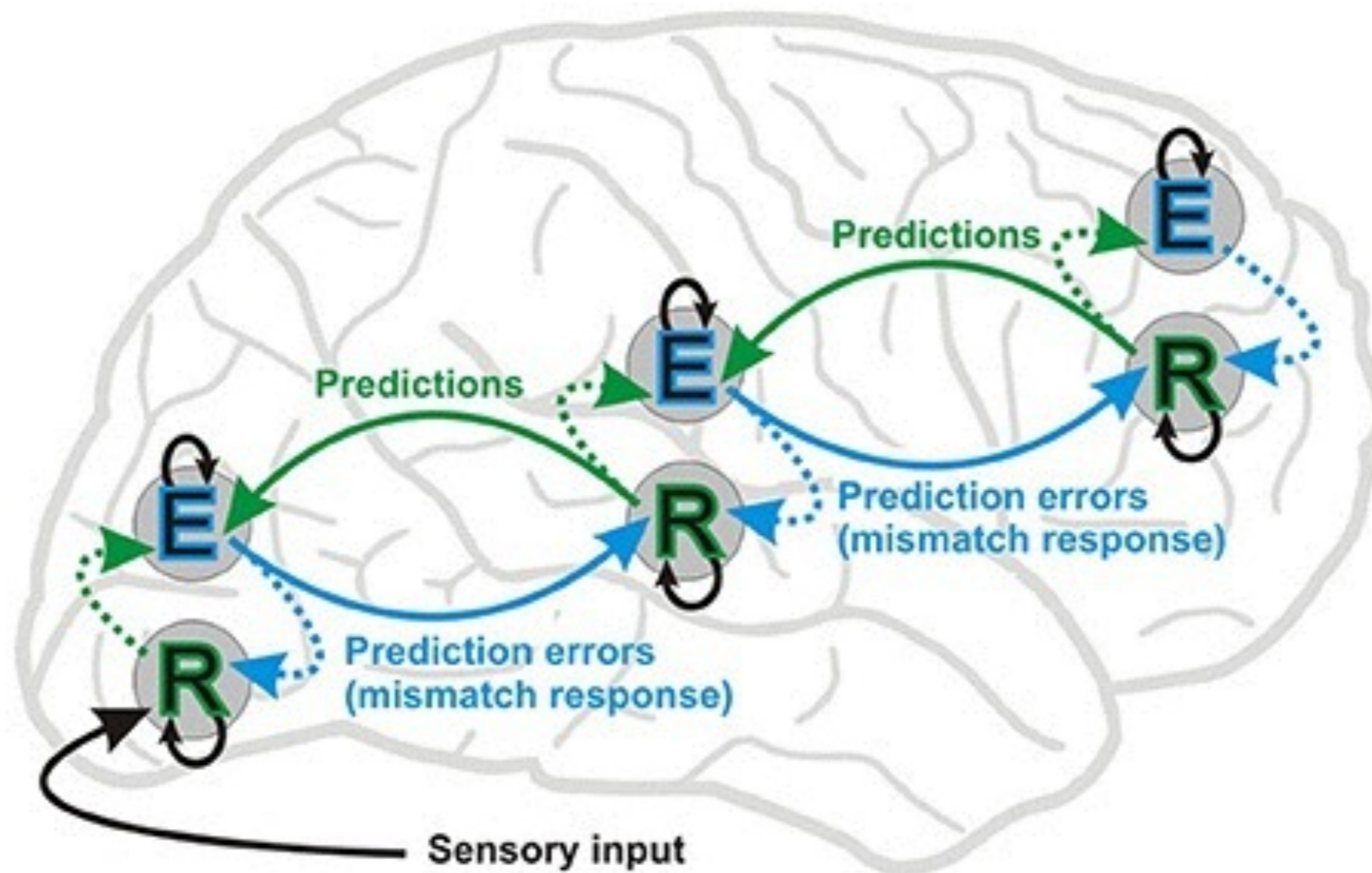
William Lotter, Gabriel Kreiman & David Cox

Harvard University, Cambridge, USA

Article overview by Ilya Kuzovkin

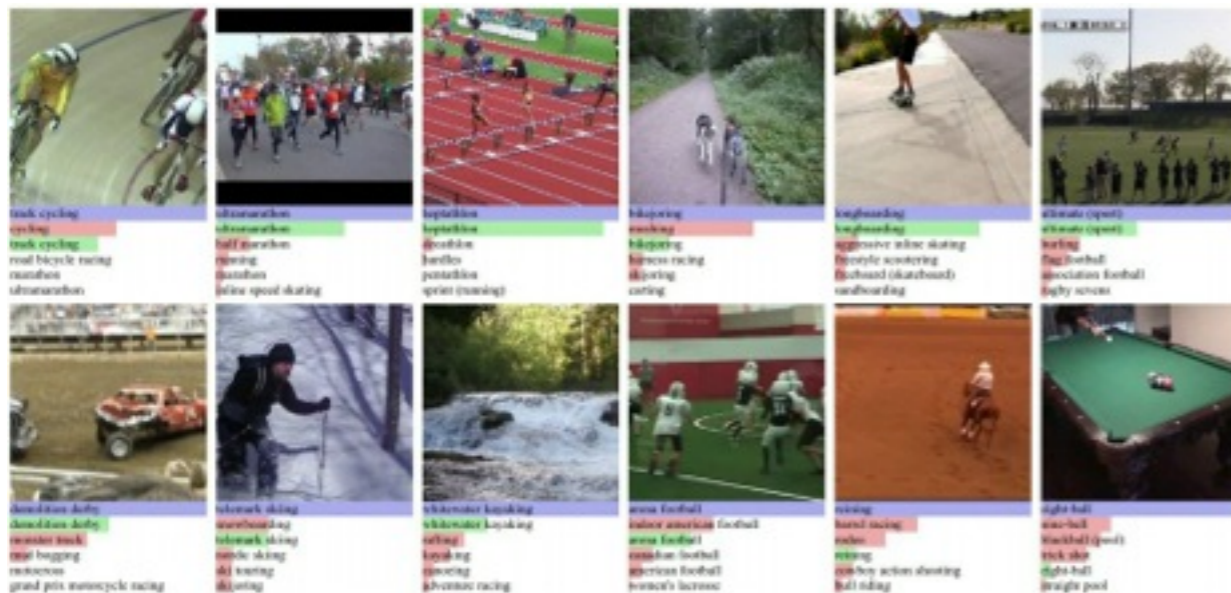
Computational Neuroscience Seminar
University of Tartu
2015





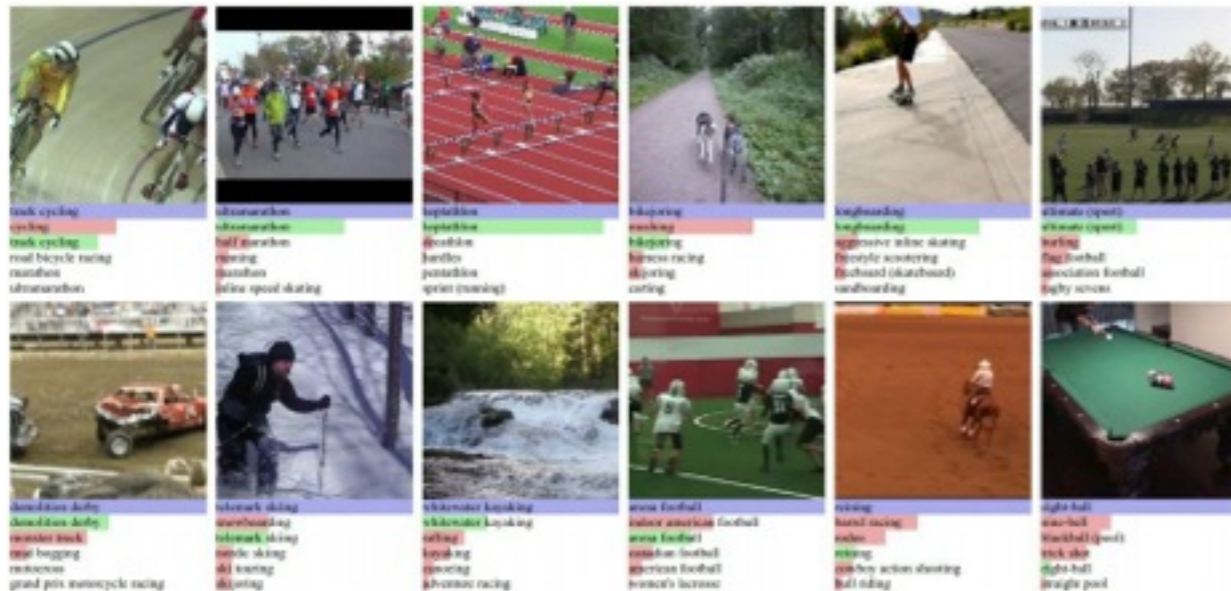
The idea of *predictive coding* in neuroscience

“state-of-the-art deep learning models rely on millions of labeled training examples to learn”

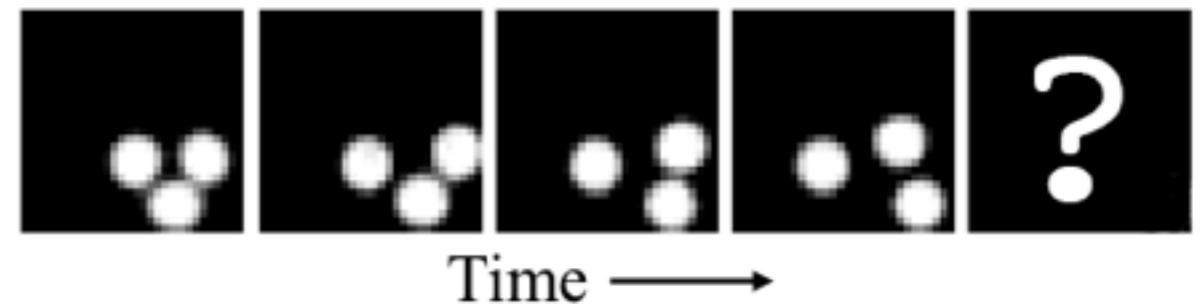


“in contrast to biological systems, where learning is largely unsupervised”

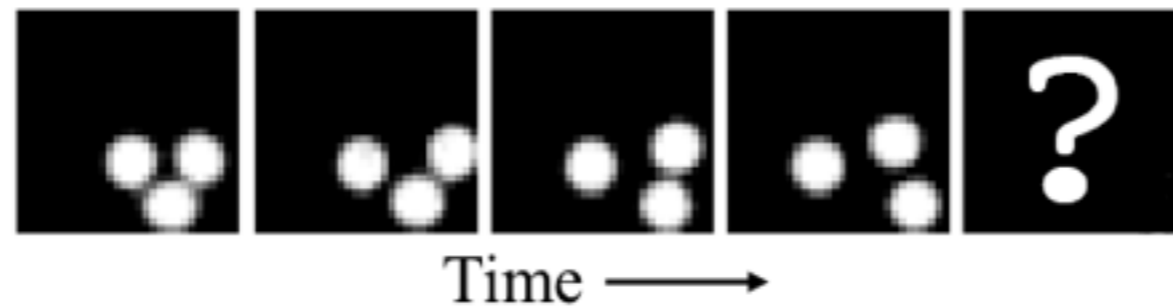
“state-of-the-art deep learning models rely on millions of labeled training examples to learn”



“we explore the idea that prediction is not only a useful end-goal, but may also serve as a powerful unsupervised learning signal”



“in contrast to biological systems, where learning is largely unsupervised”

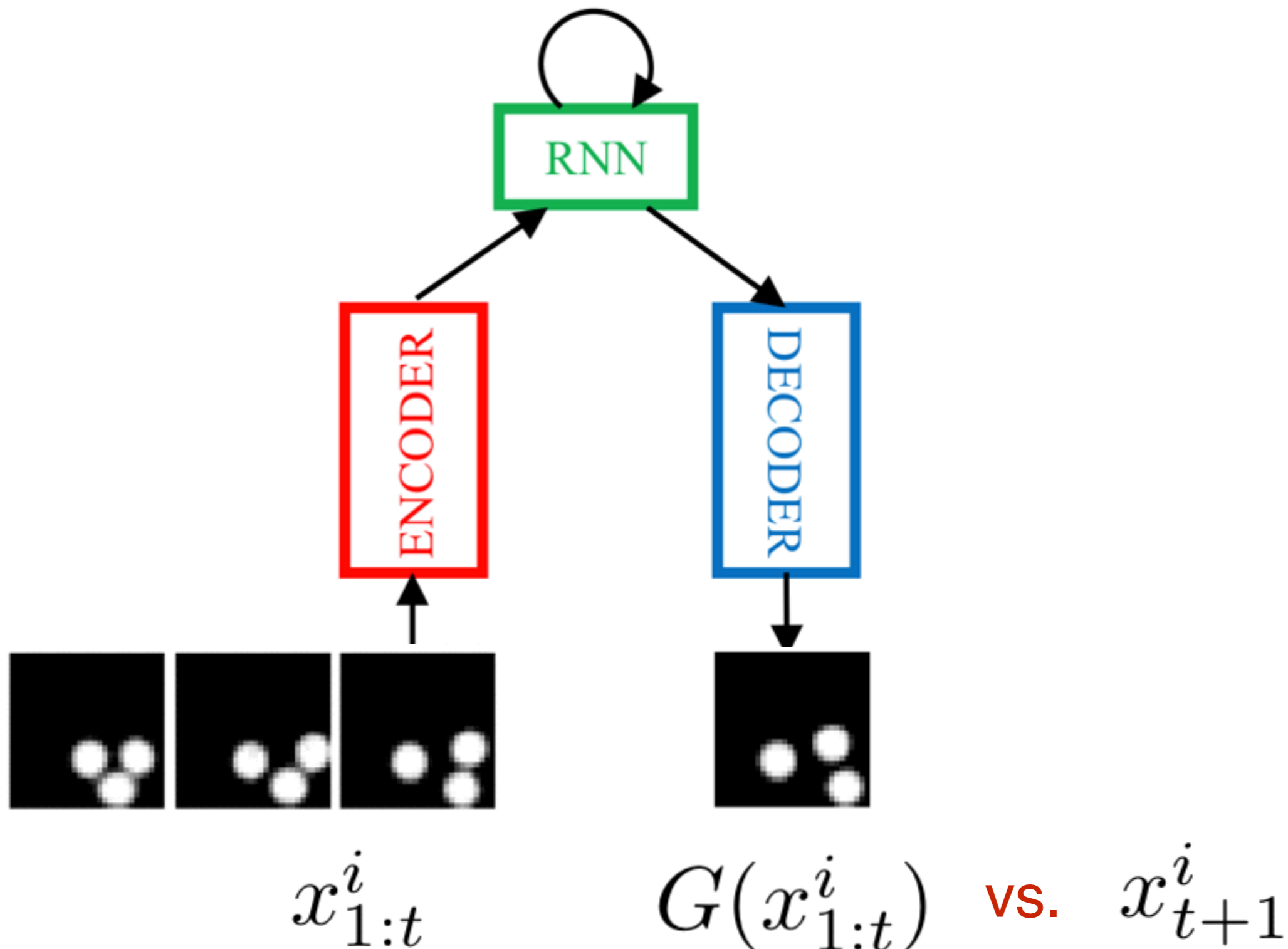


PART I

THE IDEA OF PREDICTIVE ENCODER

"prediction may also serve as a powerful unsupervised learning signal"

PREDICTIVE GENERATIVE NETWORK (a.k.a “Predictive Encoder” Palm 2012)

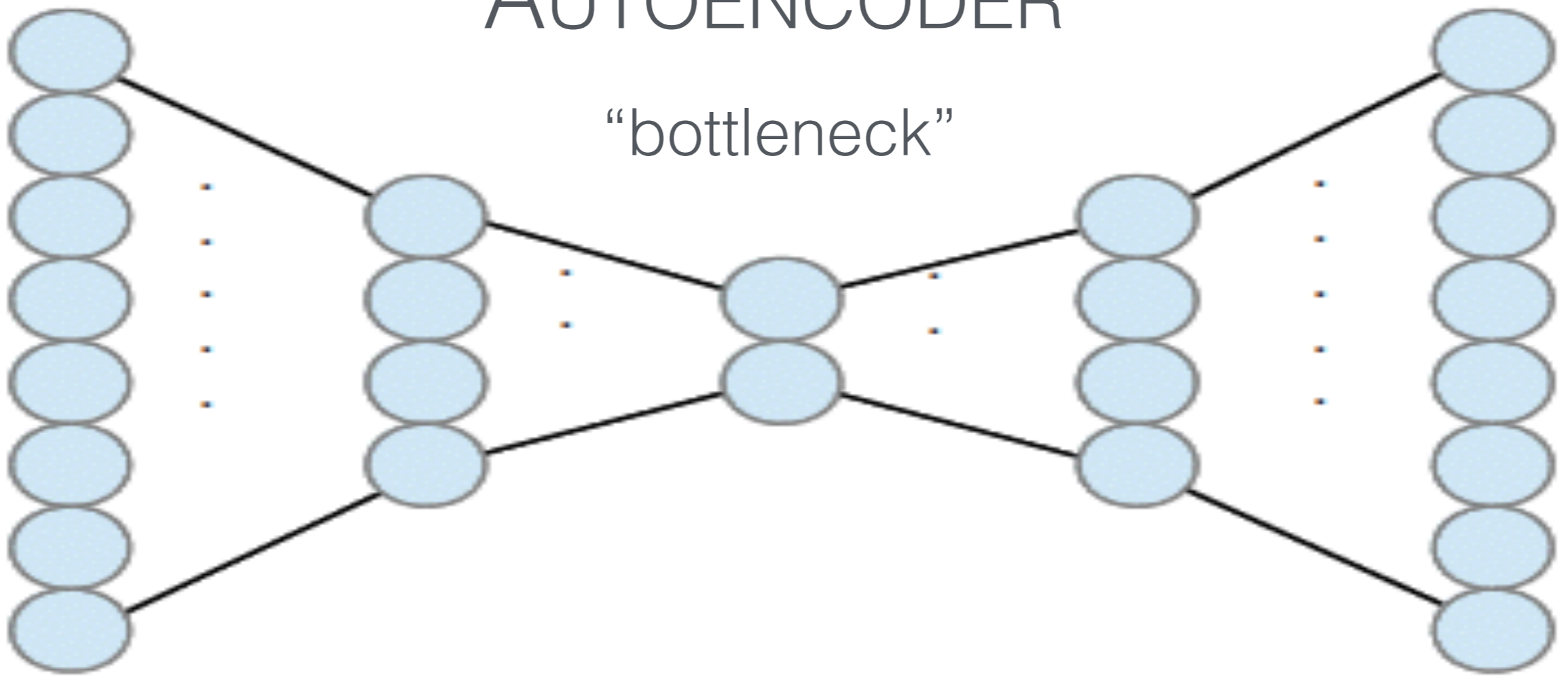


input

AUTOENCODER

output

“bottleneck”

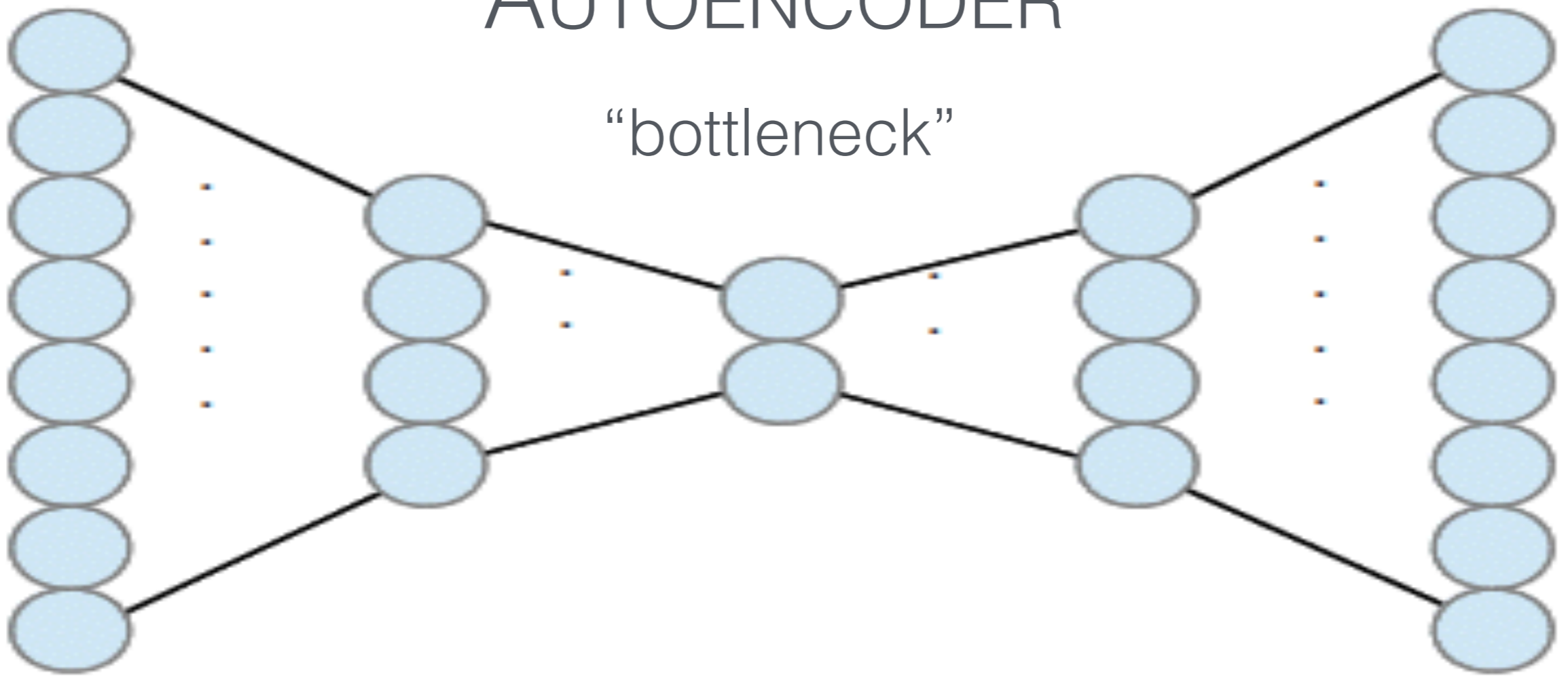


input

AUTOENCODER

output

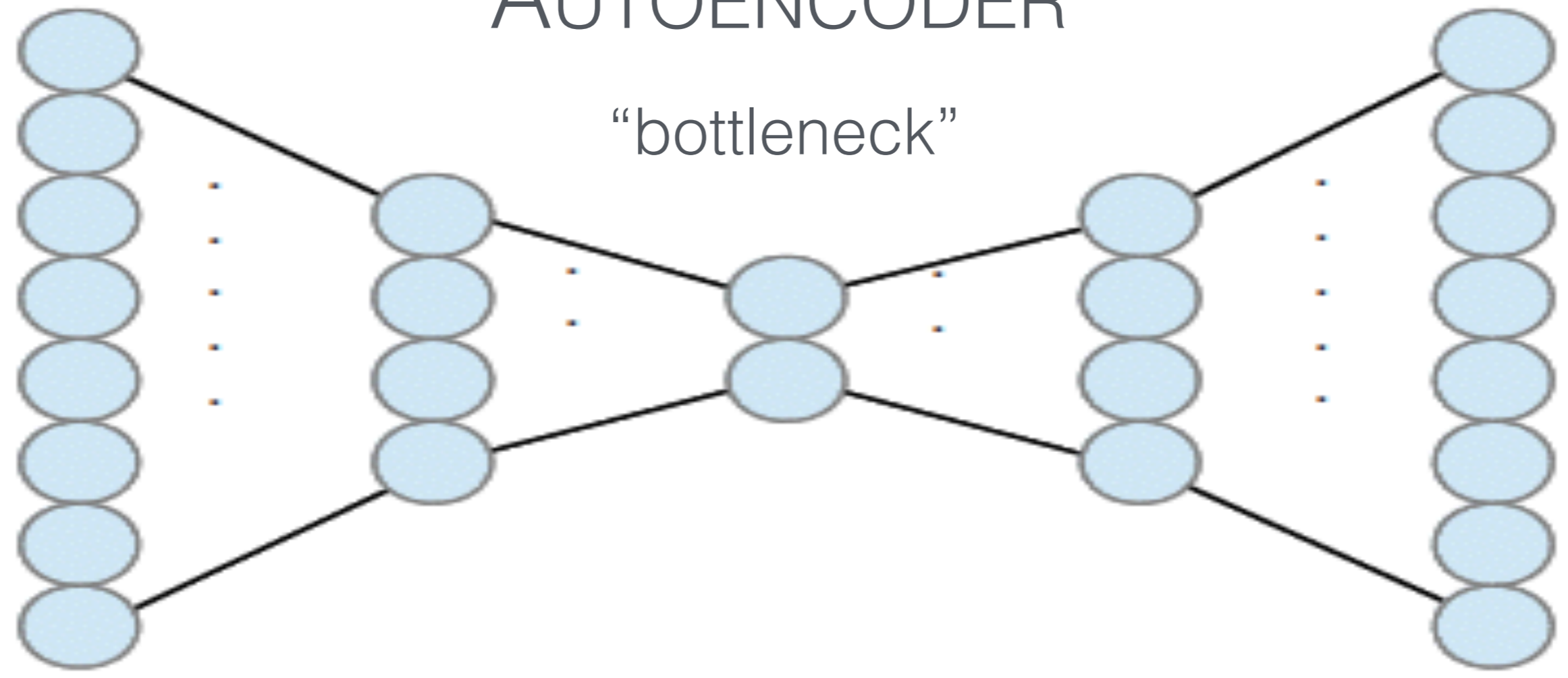
“bottleneck”



input

AUTOENCODER

output



“bottleneck”



ENCODER



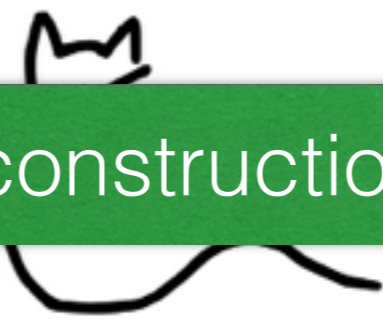
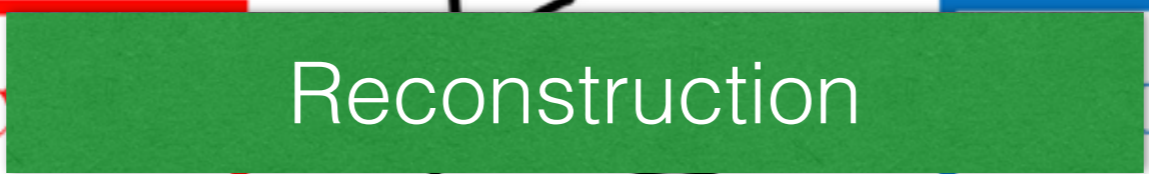
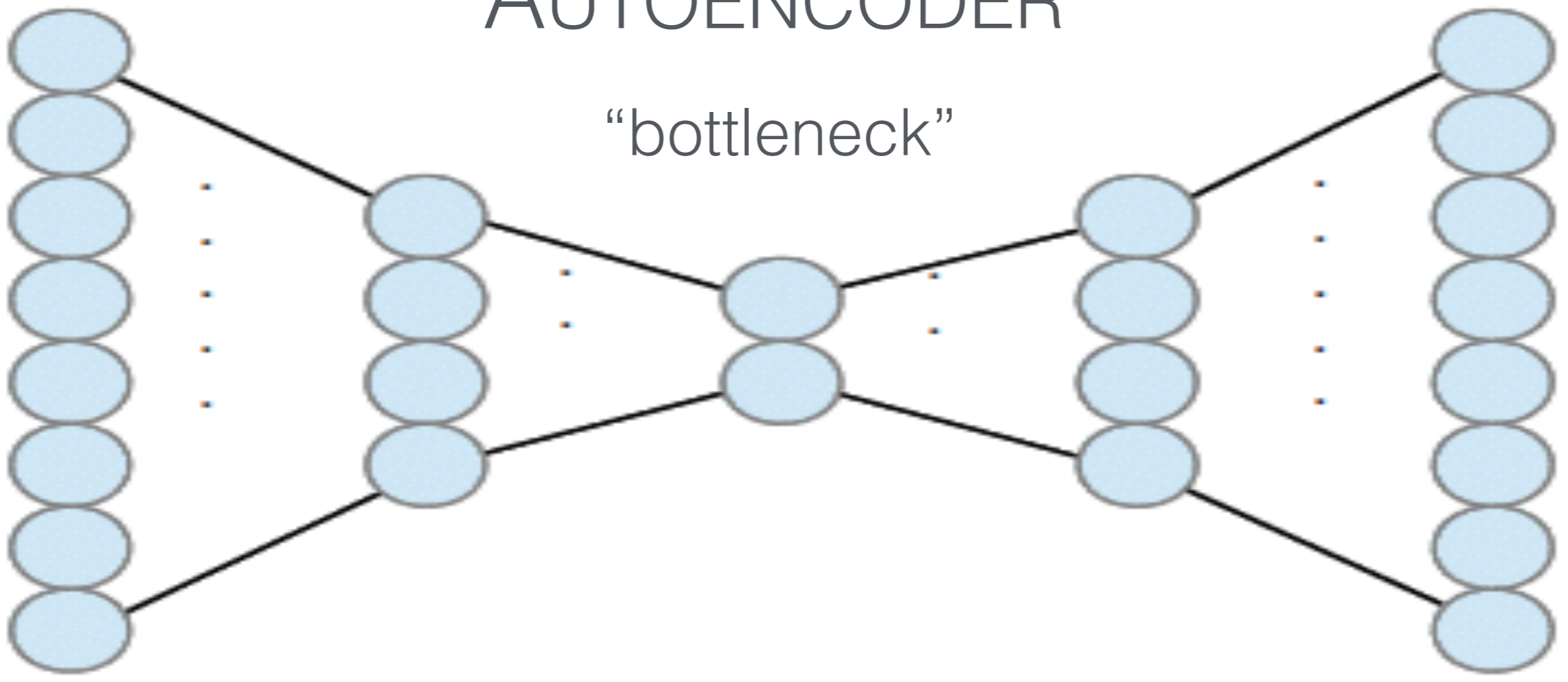
DECODER



input

AUTOENCODER

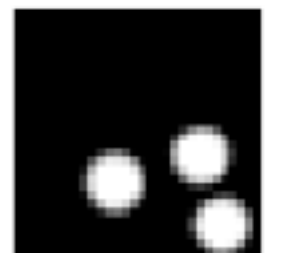
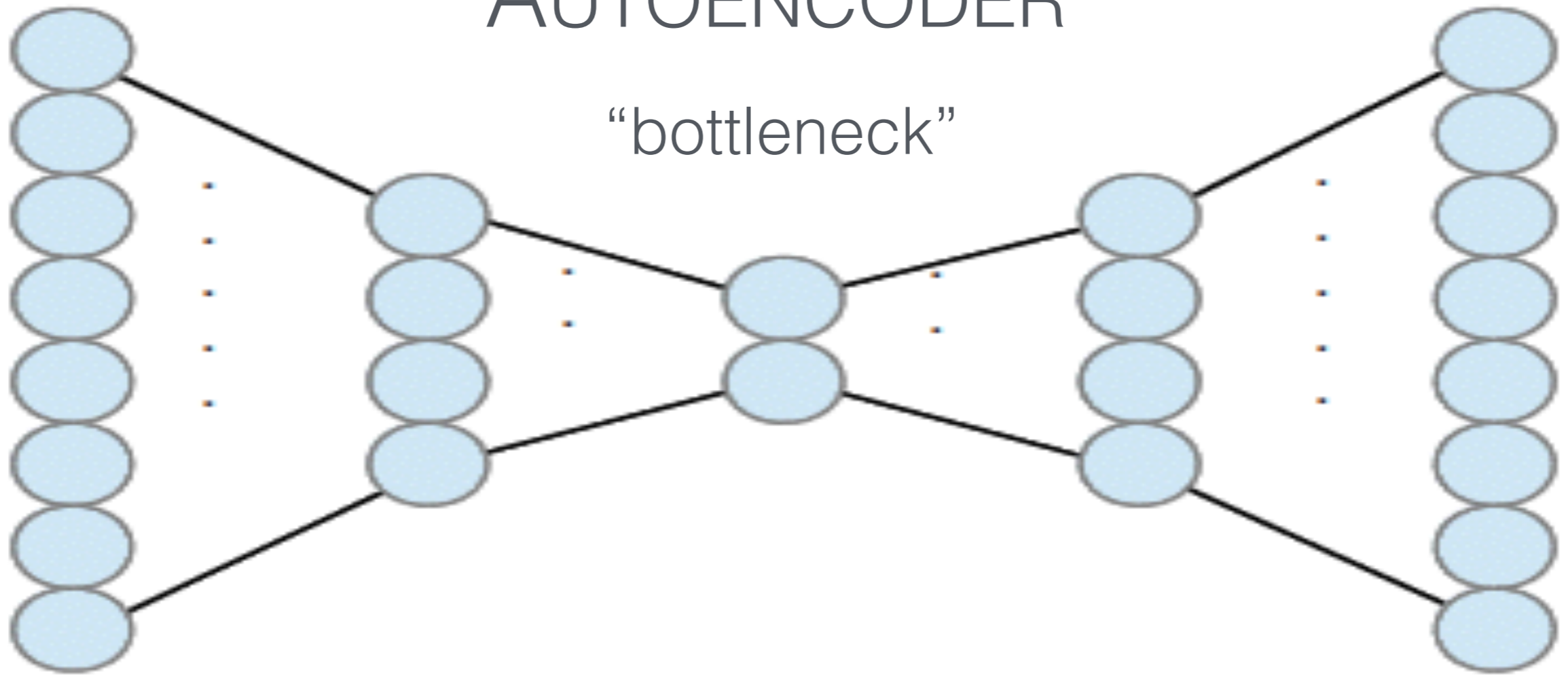
output



input

AUTOENCODER

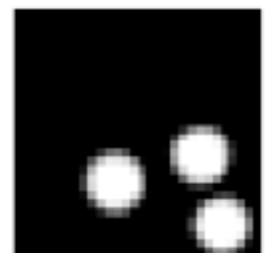
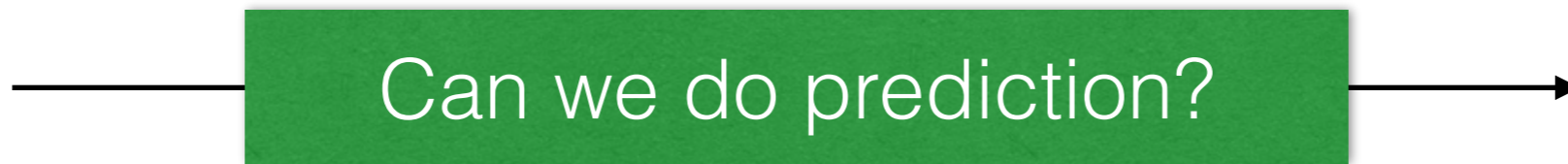
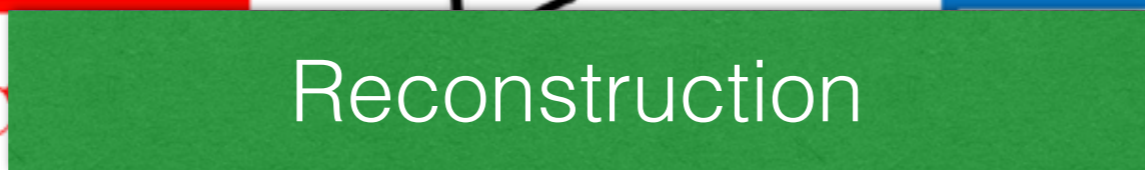
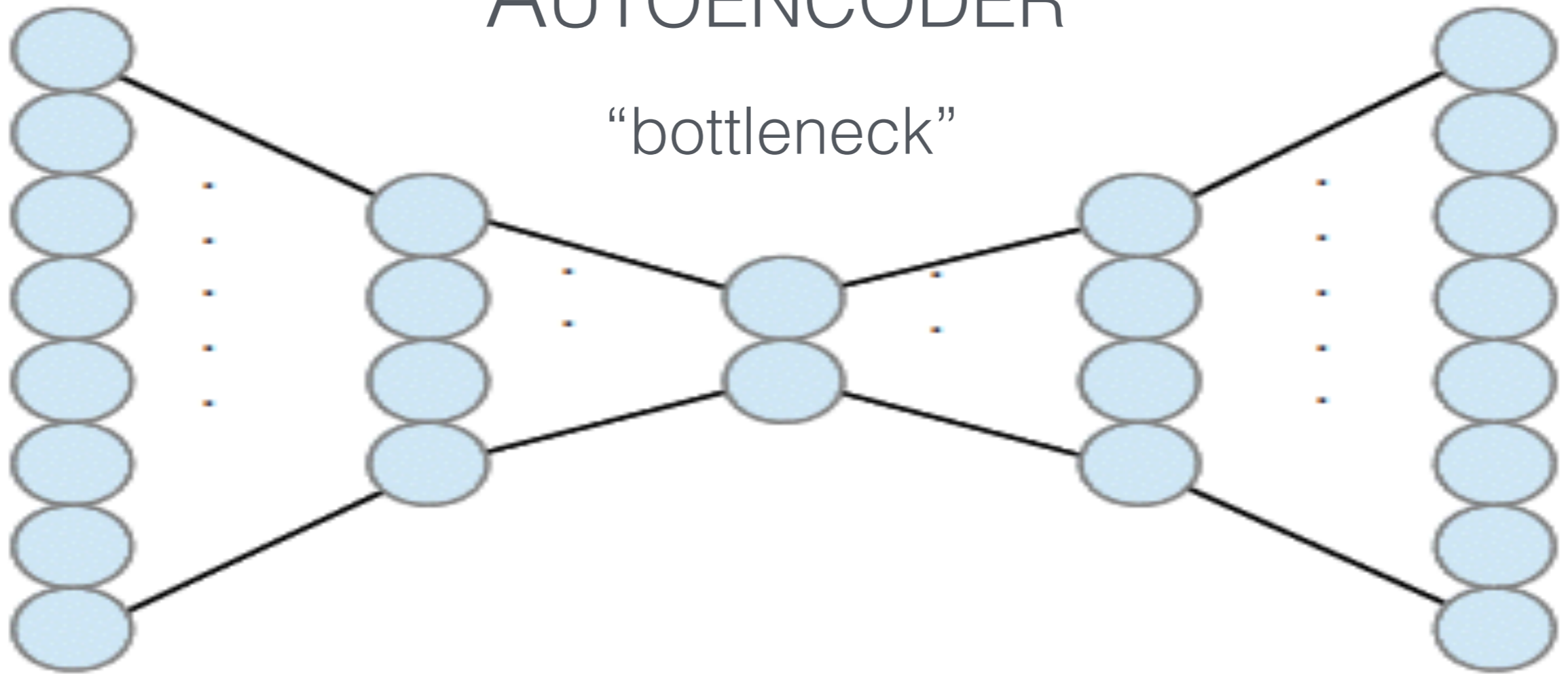
output



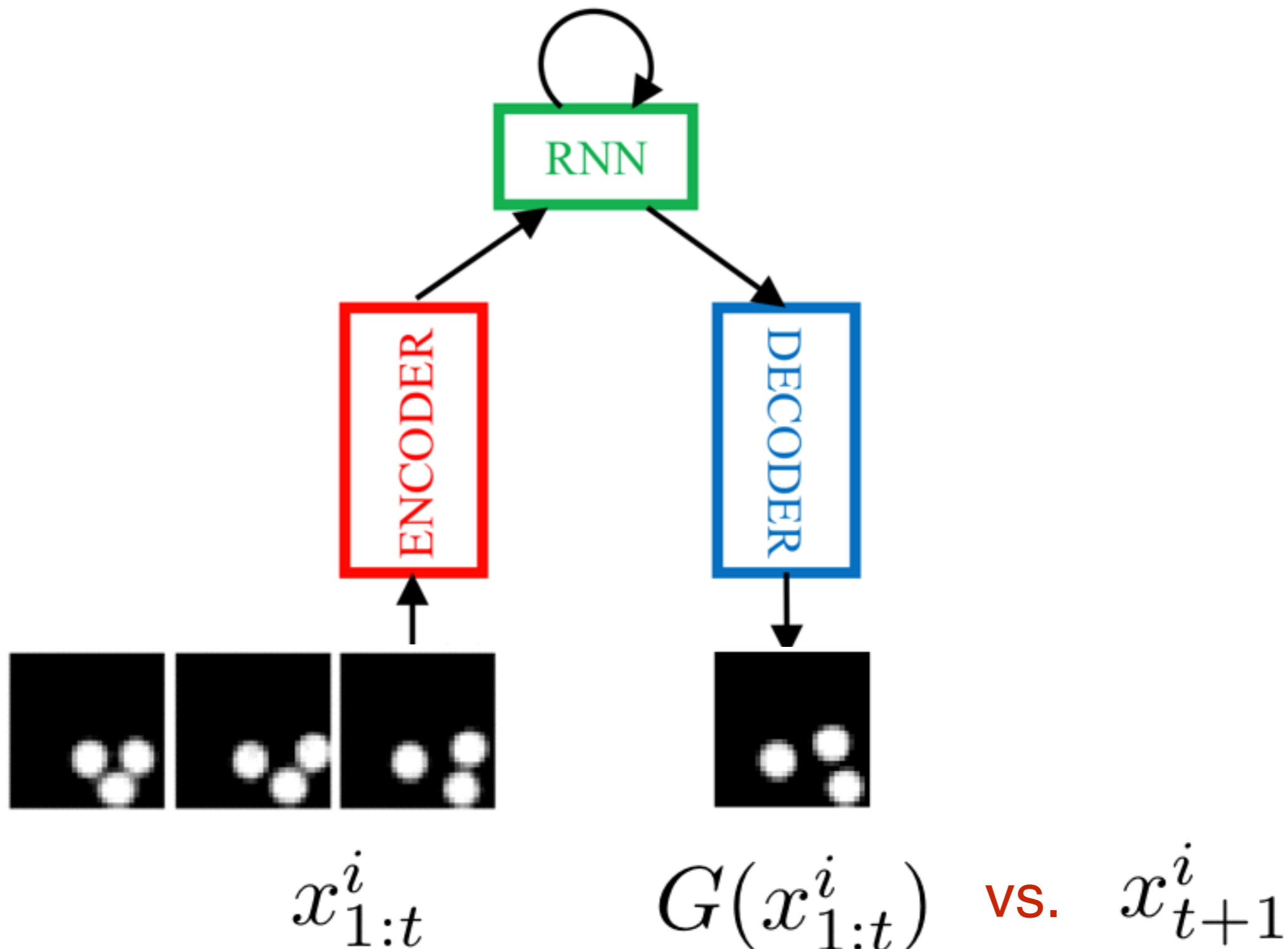
input

AUTOENCODER

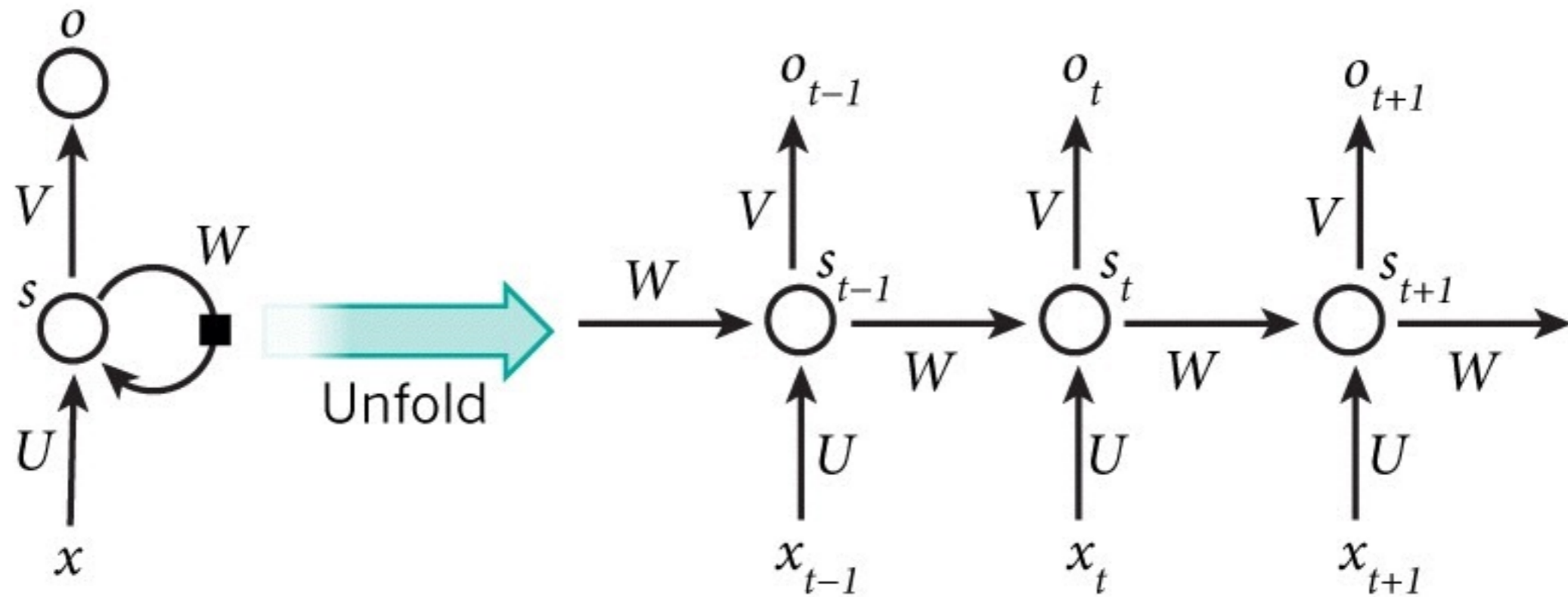
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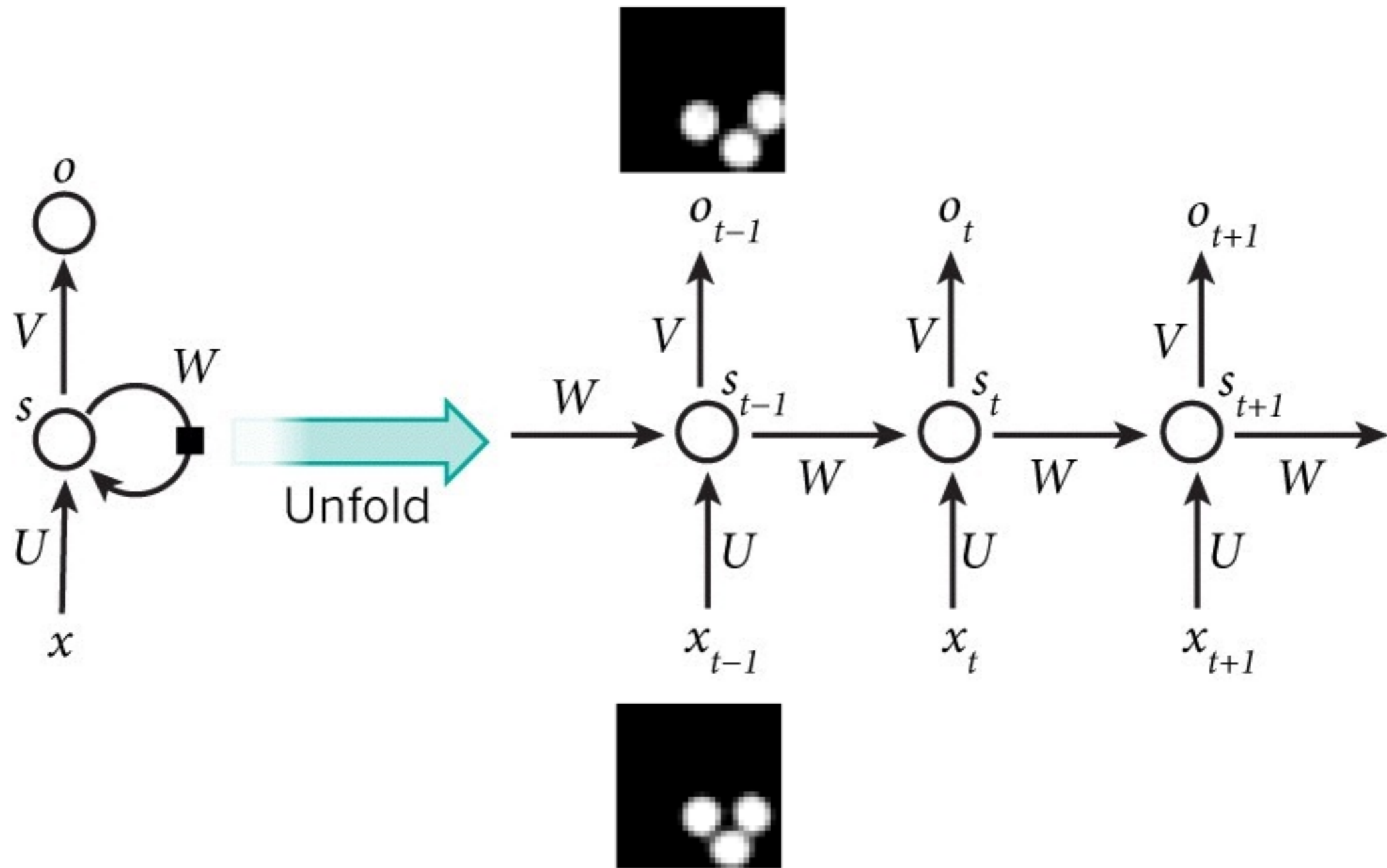
PREDICTIVE GENERATIVE NETWORK (a.k.a “Predictive Encoder” Palm 2012)



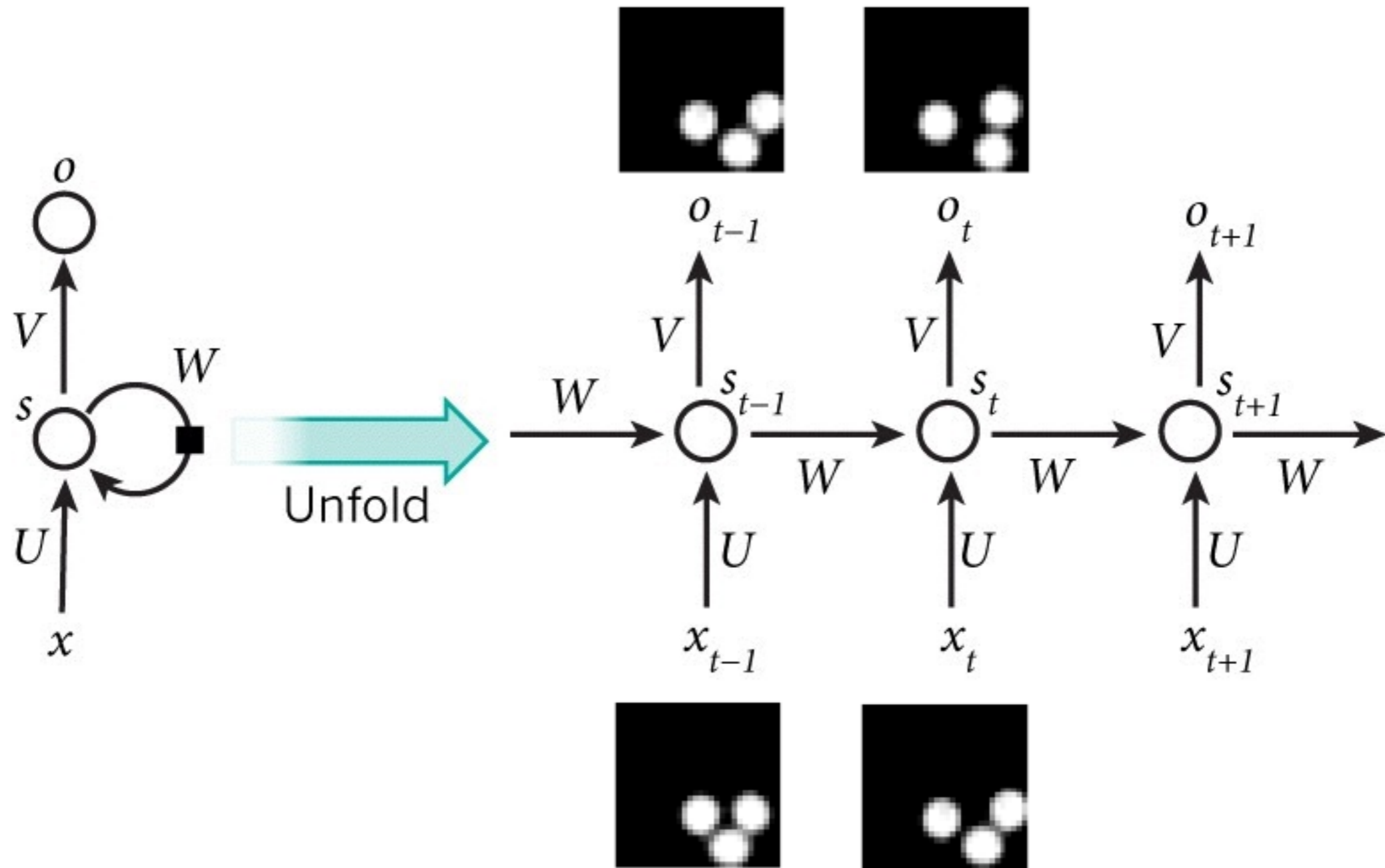
RECURRENT NEURAL NETWORK



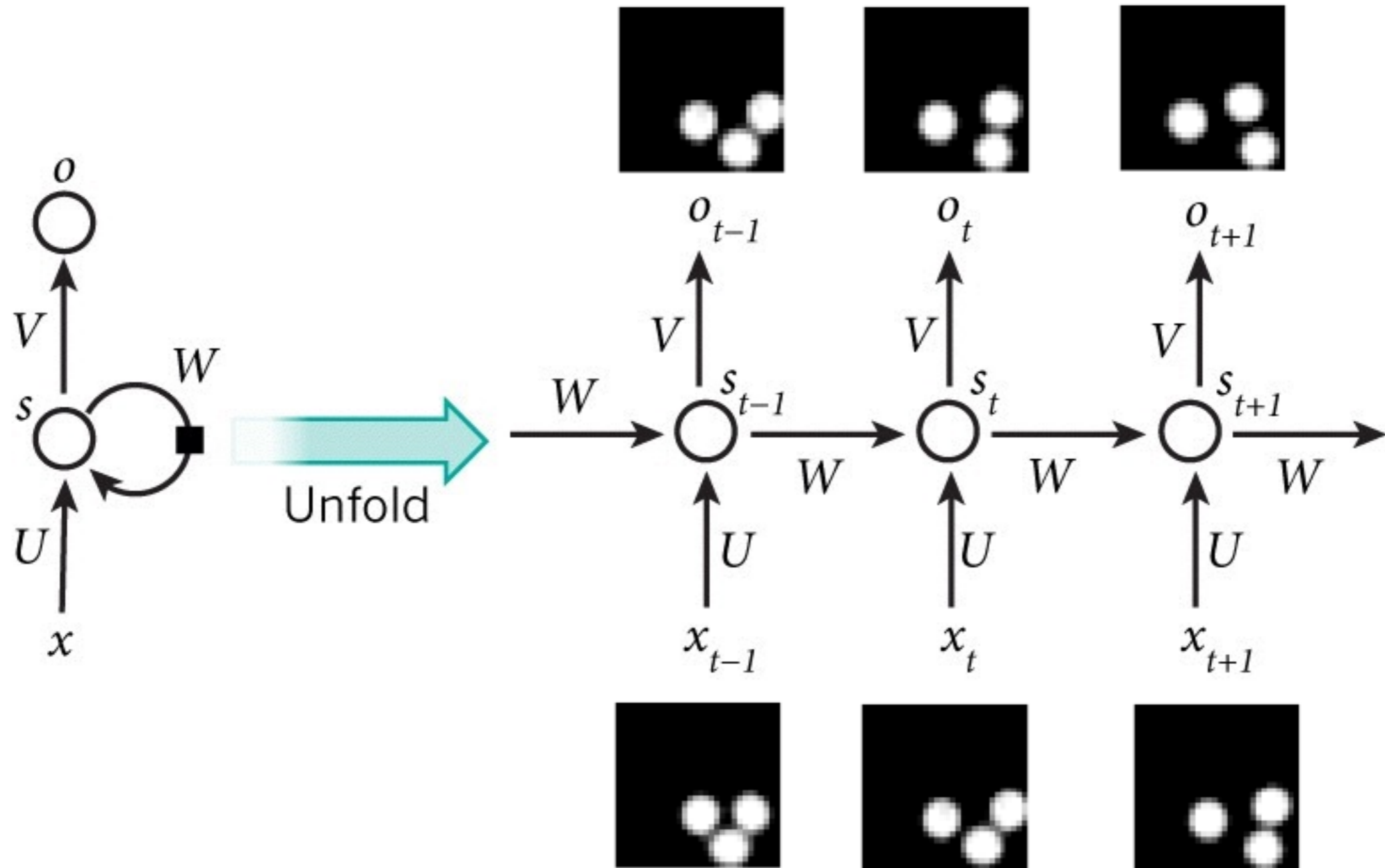
RECURRENT NEURAL NETWORK



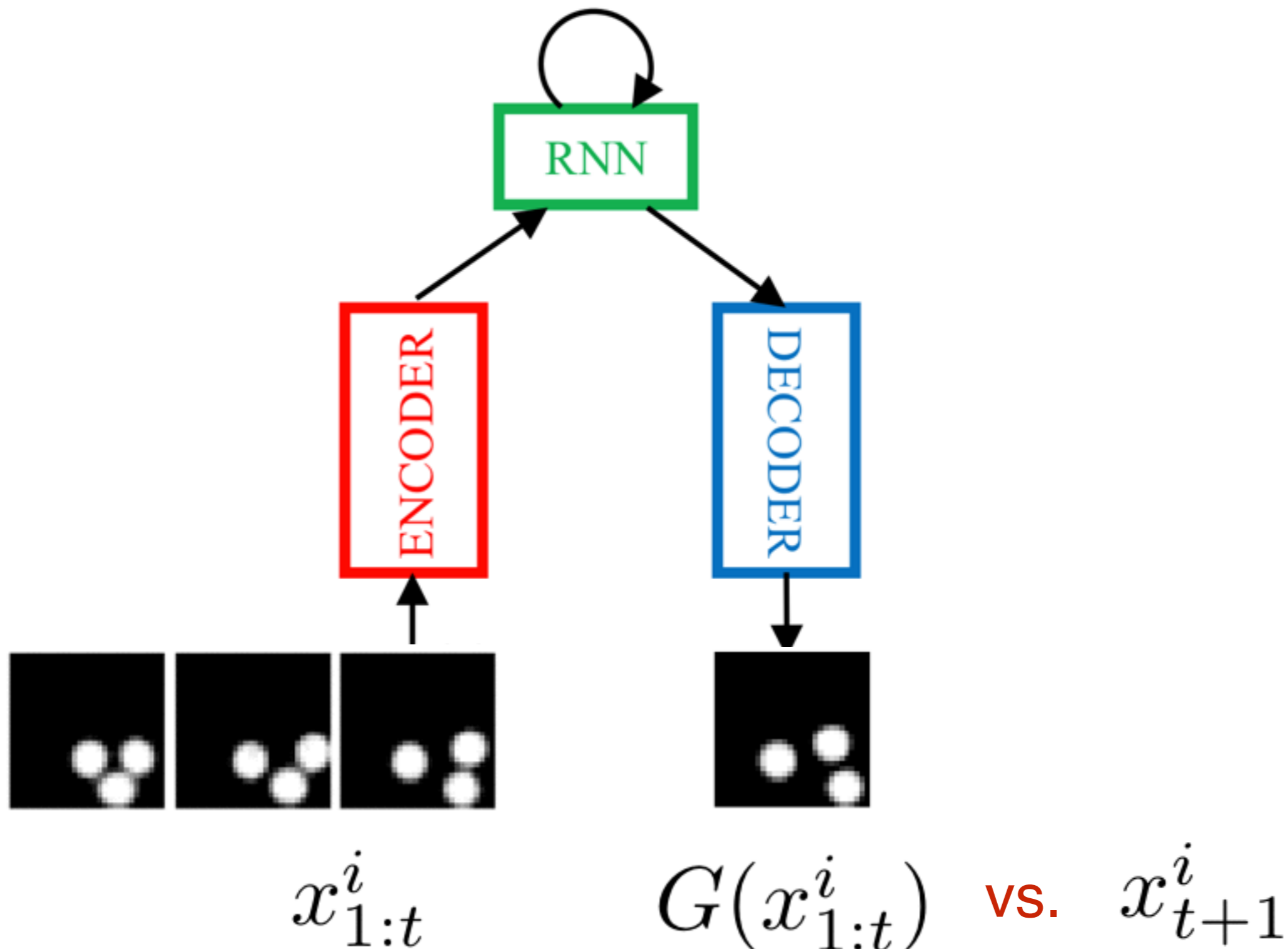
RECURRENT NEURAL NETWORK



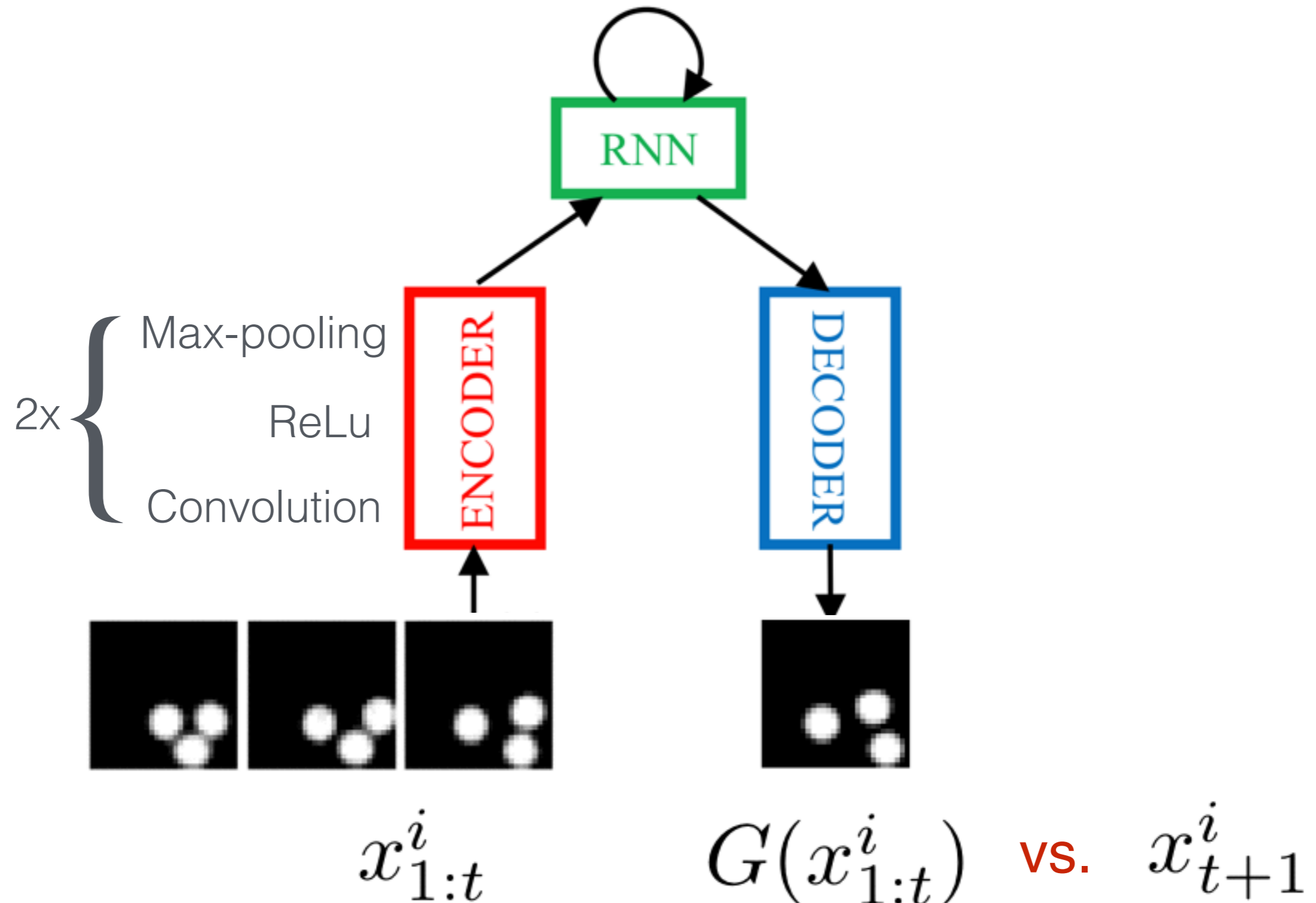
RECURRENT NEURAL NETWORK



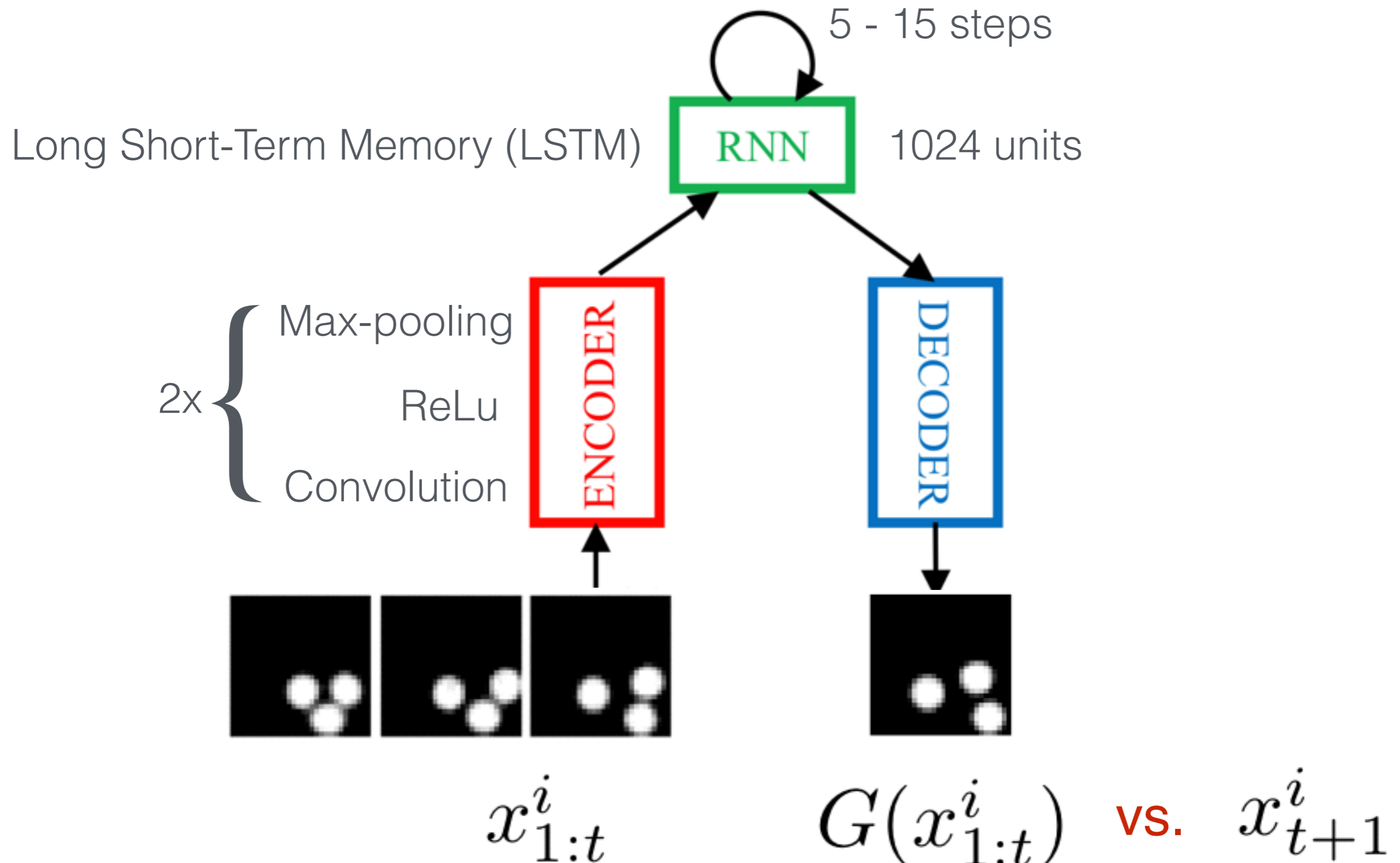
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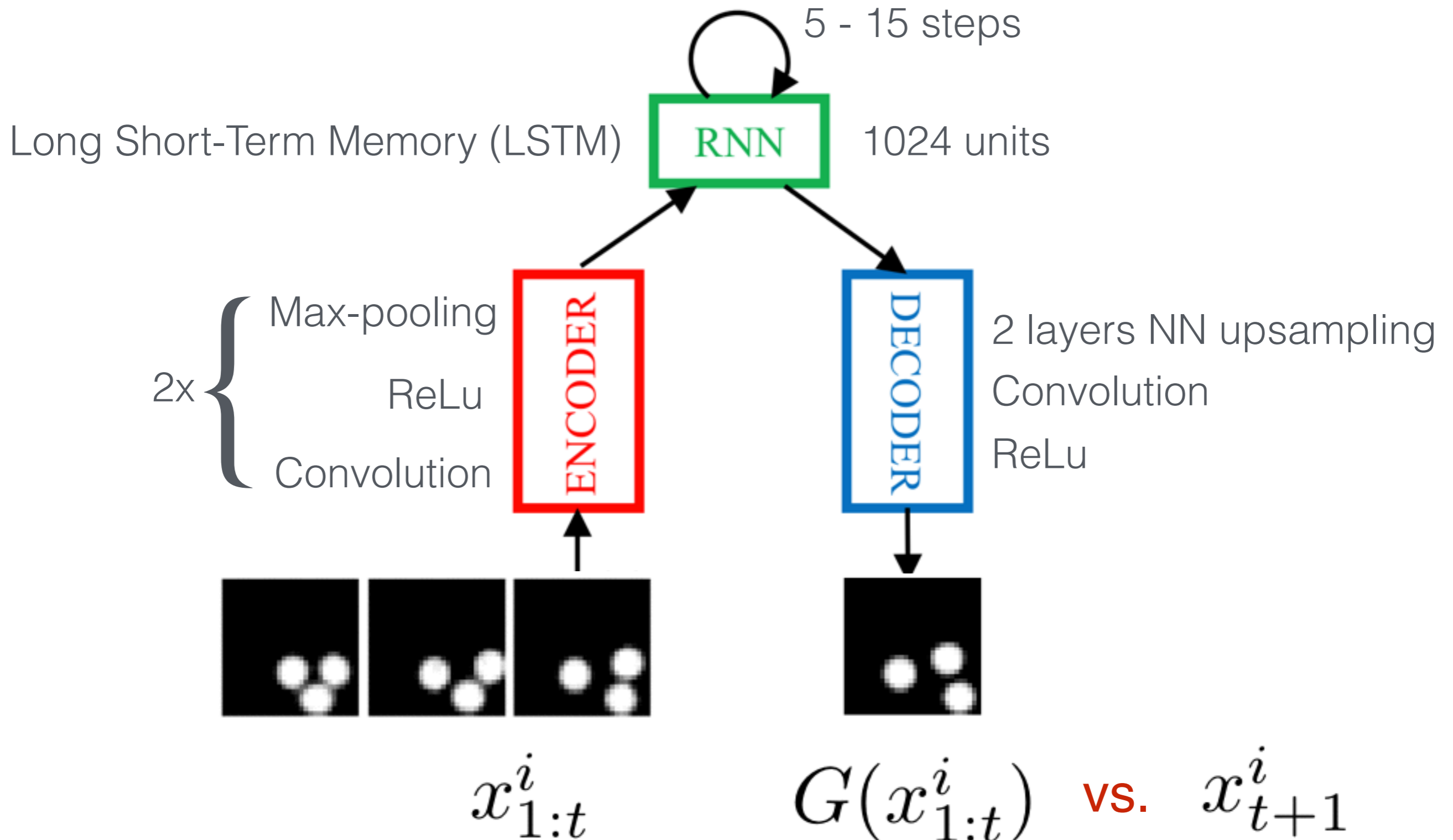
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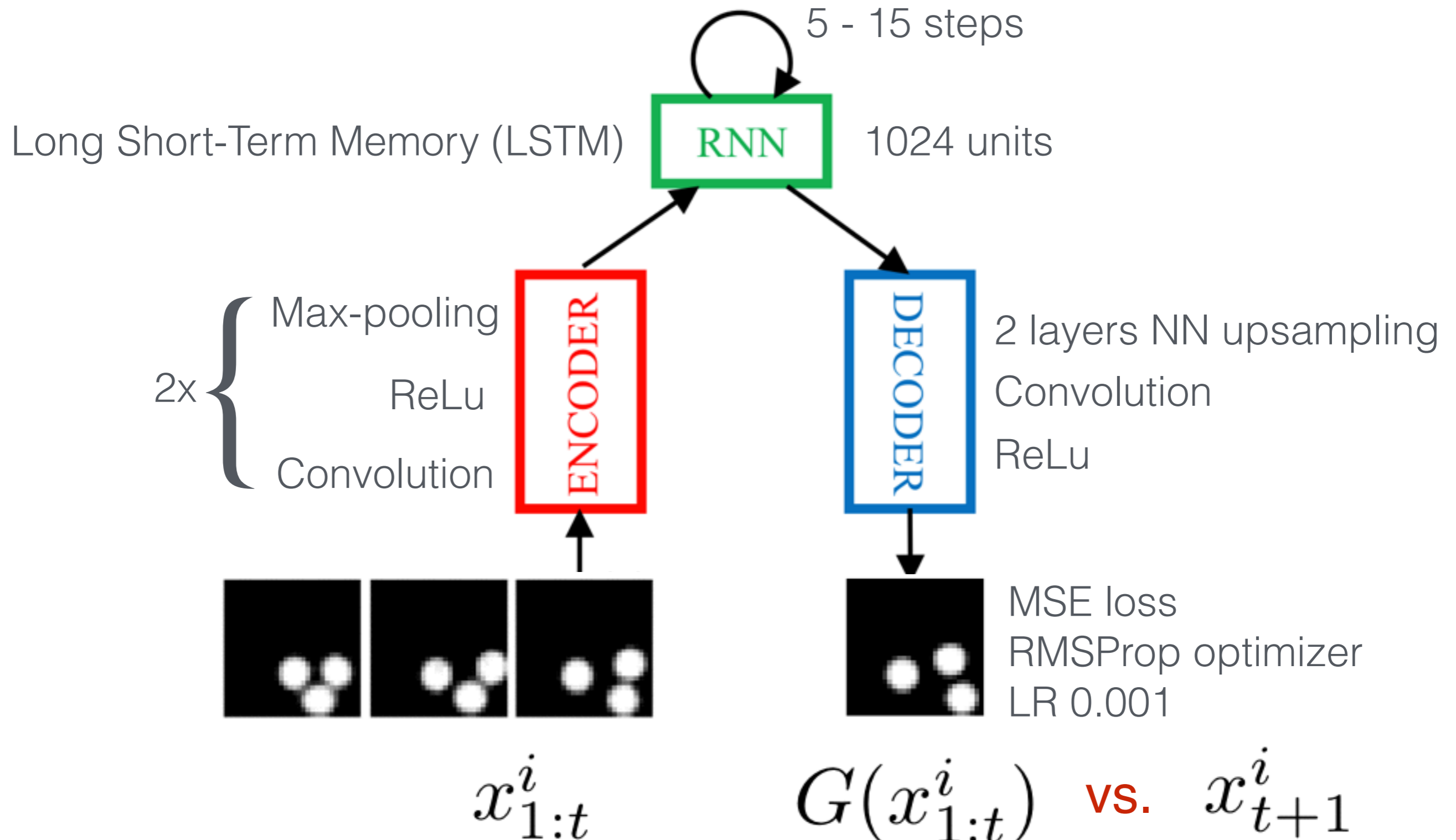
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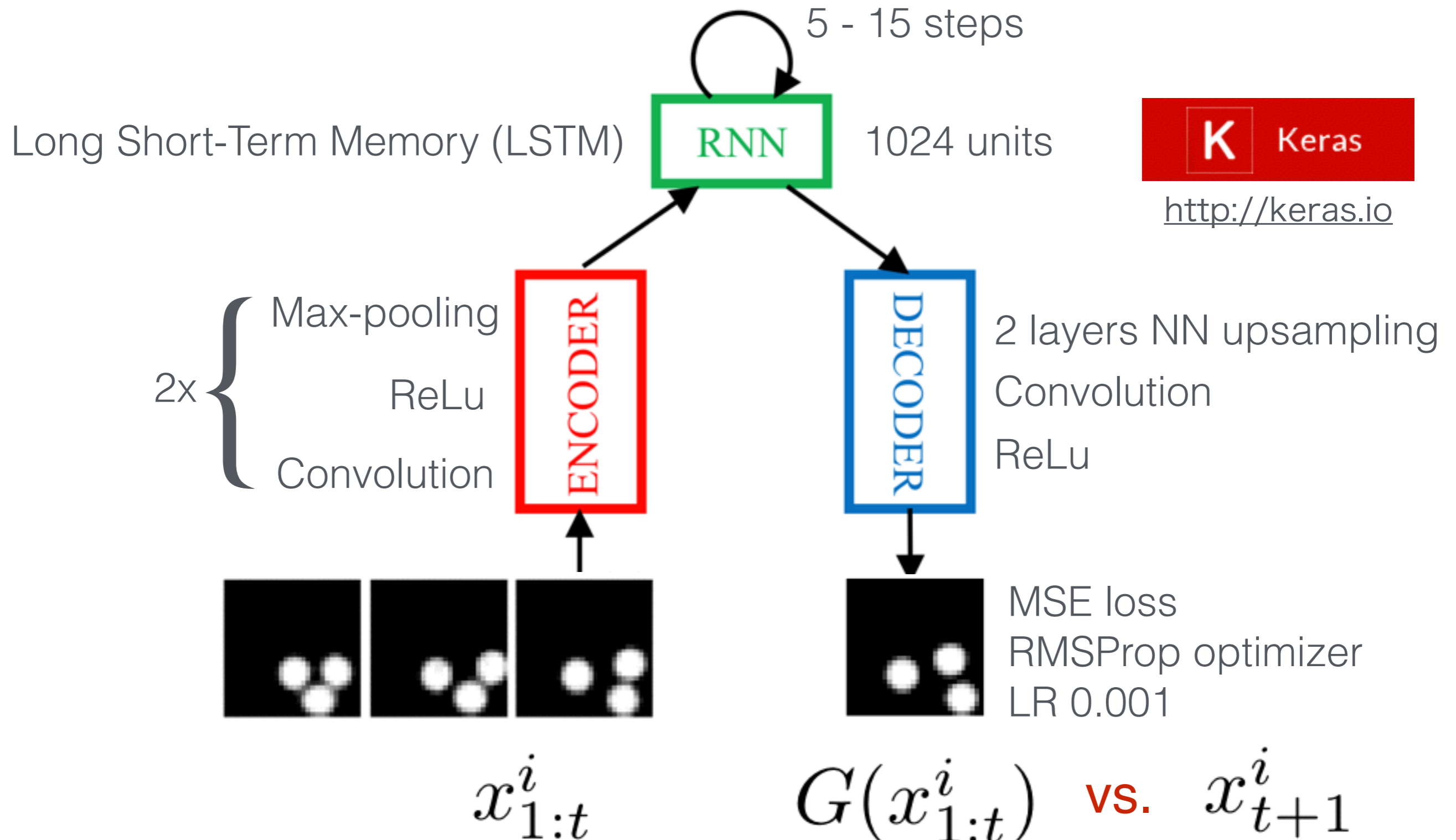
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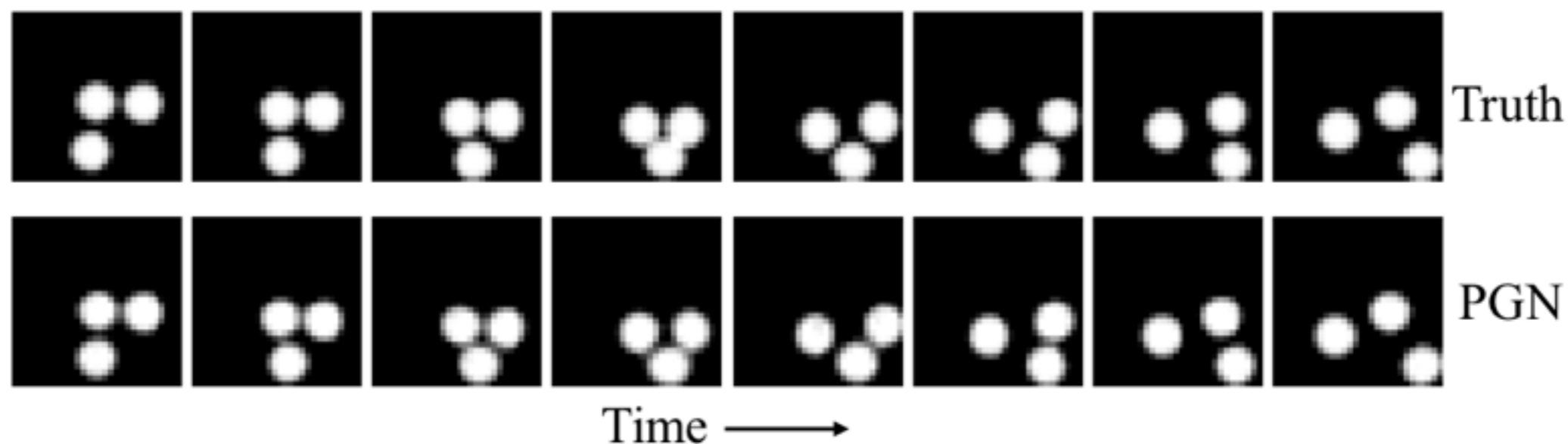
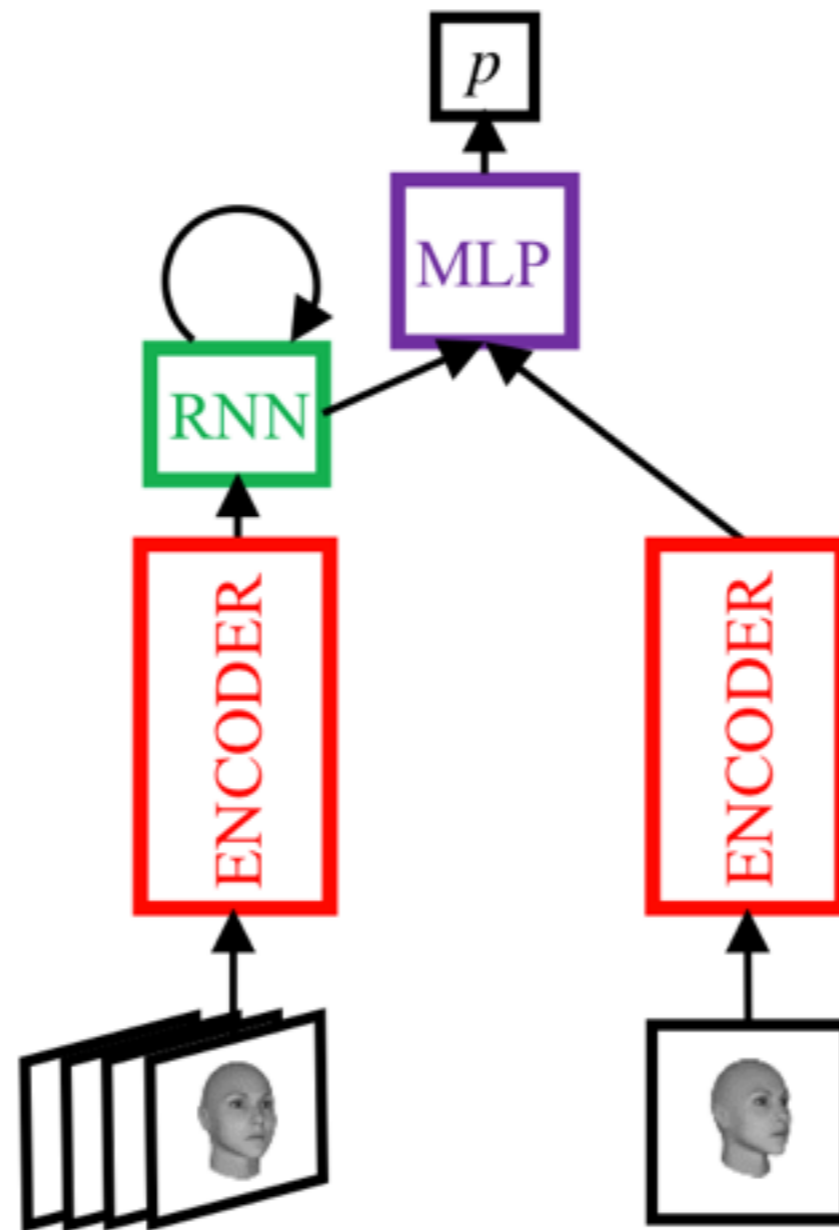


Figure 2: Example prediction sequence the for bouncing balls dataset. Predictions are repeatedly generated one step ahead using the prior ten frames as input.

Table 1: Average prediction error for the bouncing balls dataset. [†](Gan et al., 2015)
[◇](Mittelmann et al., 2014)

Model	Error
PGN	0.65 ± 0.11
DTsBN [†]	2.79 ± 0.39
SRTRBM [◇]	3.31 ± 0.33
RTRBM [◇]	3.88 ± 0.33

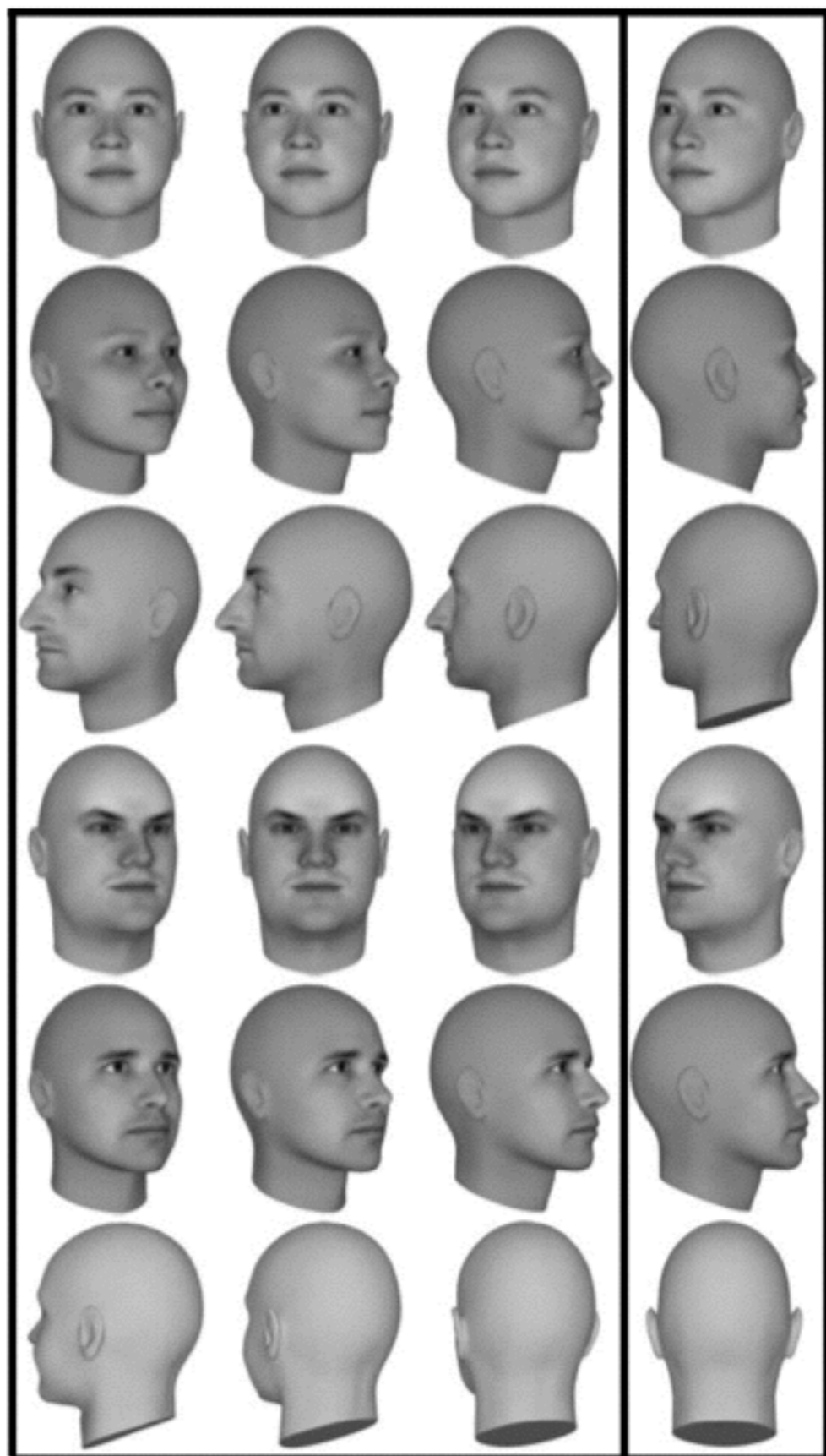


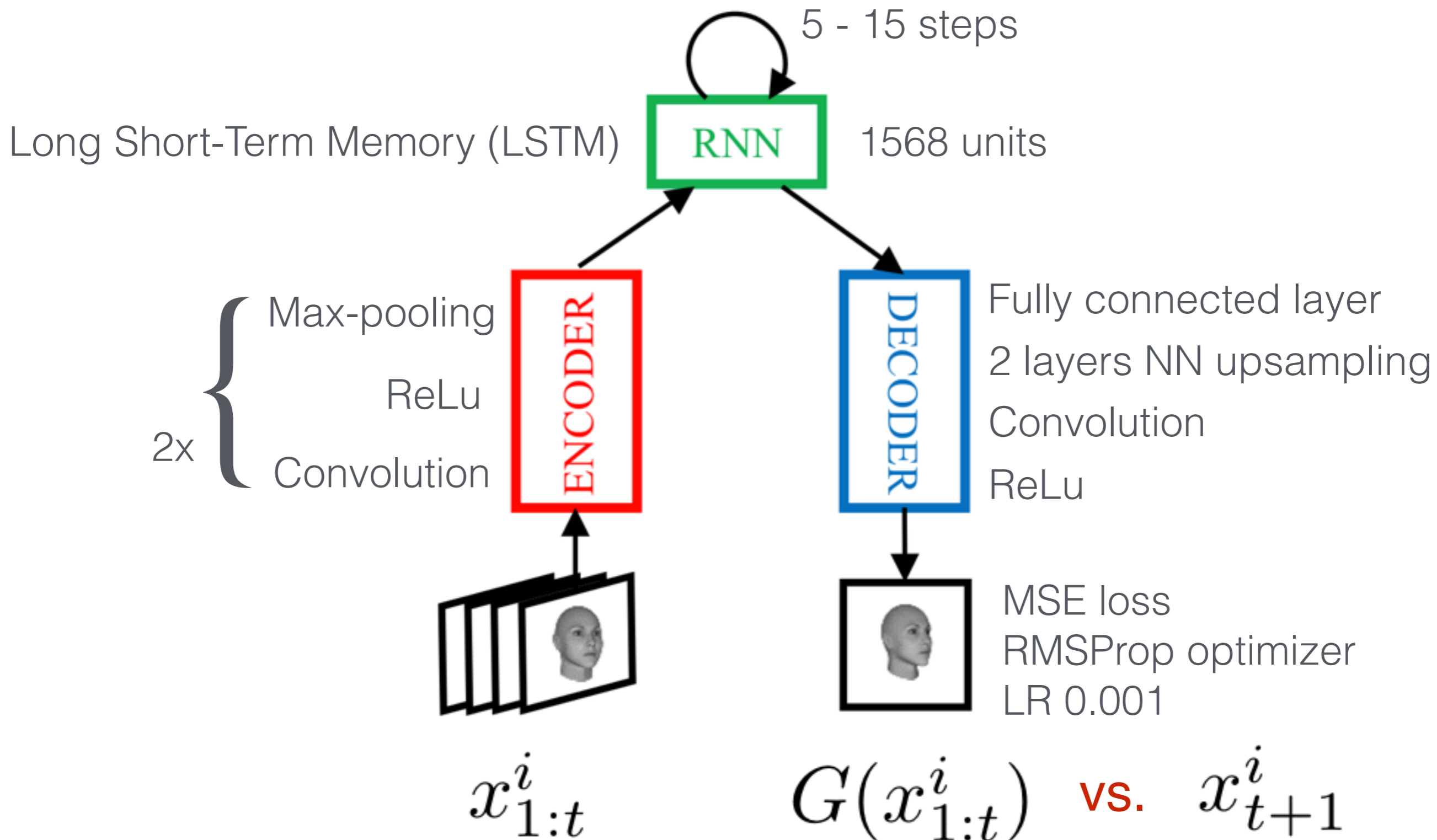
PART II ADVERSARIAL LOSS

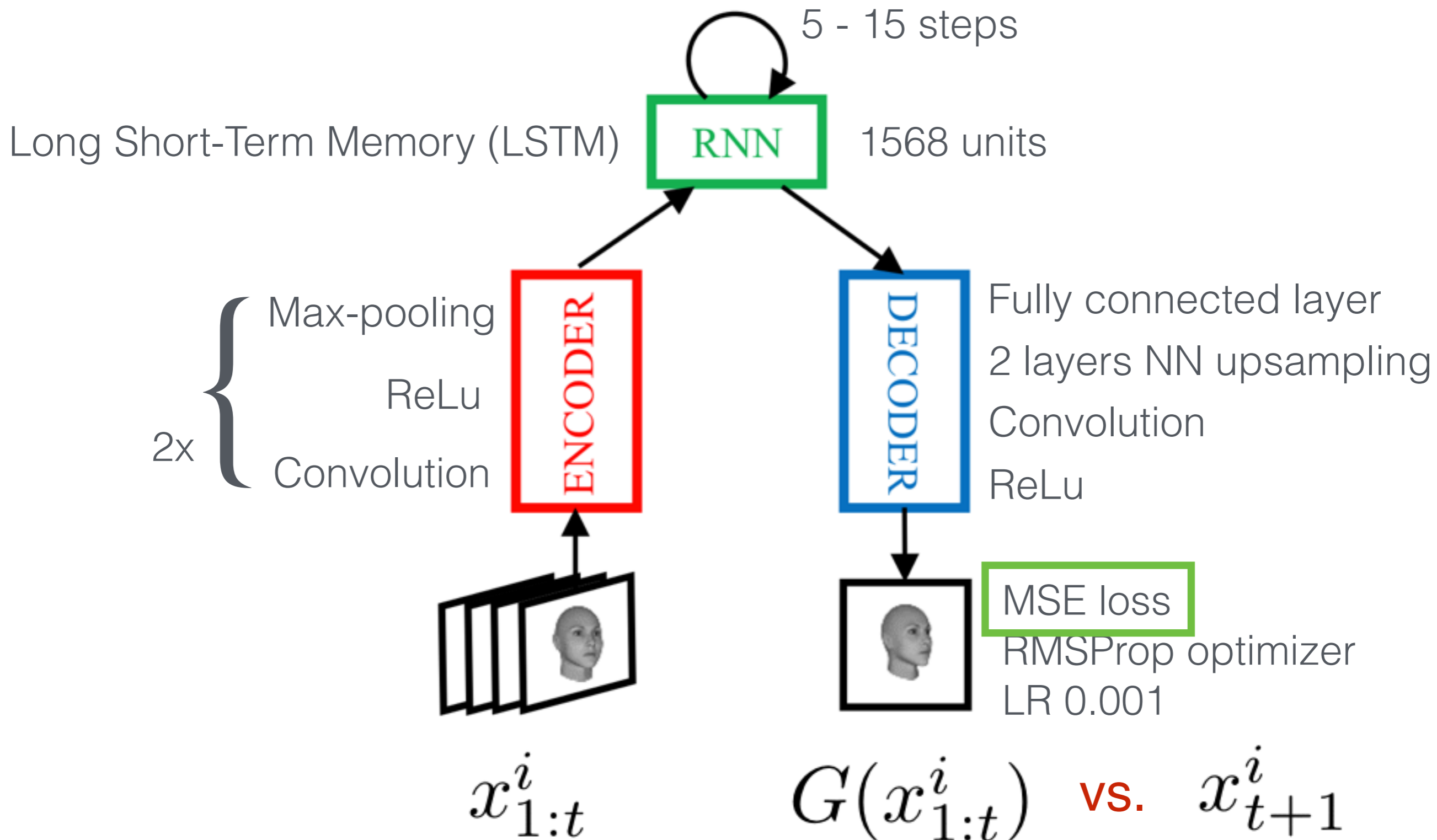
"the generator is trained to maximally confuse the adversarial discriminator"

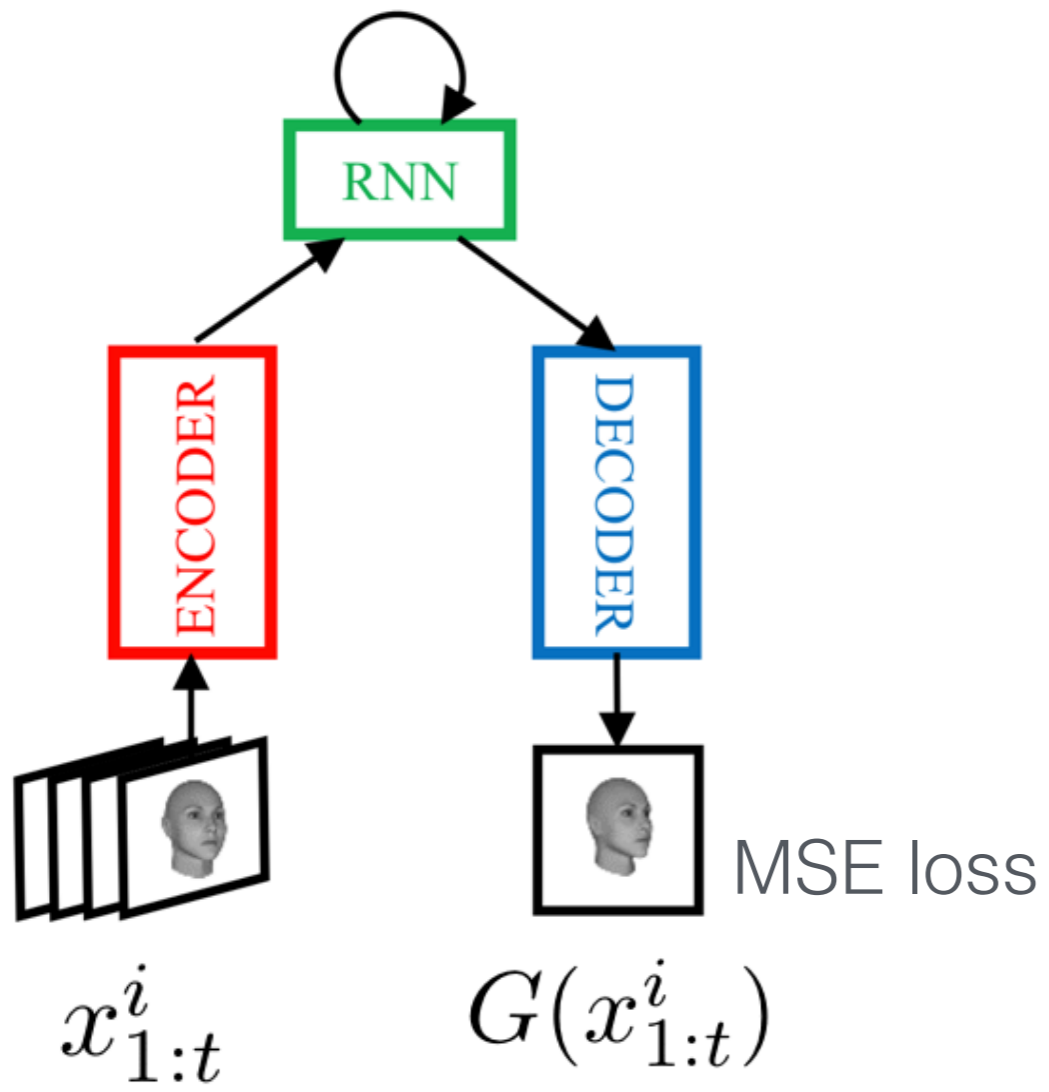
Preceding Frames

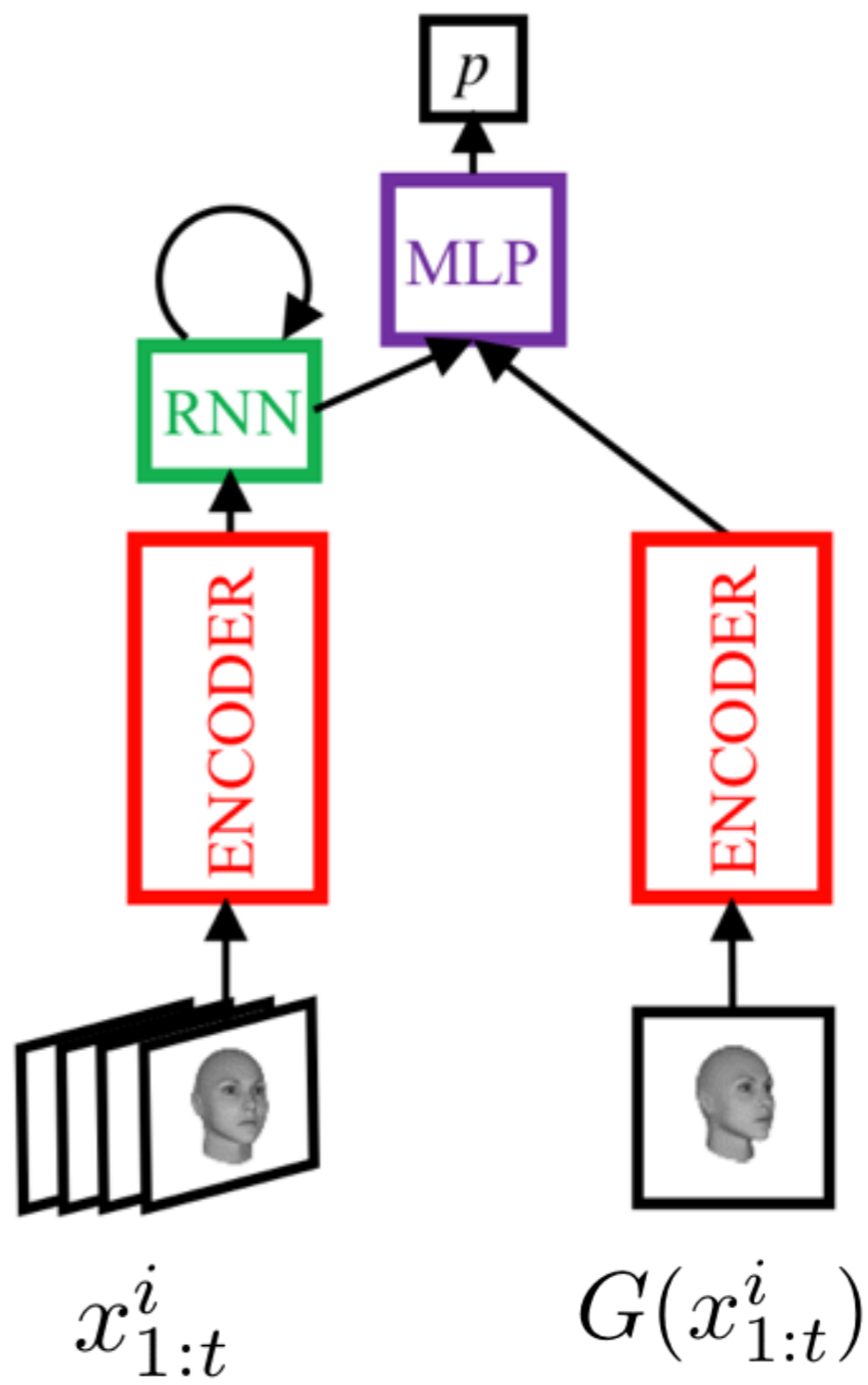
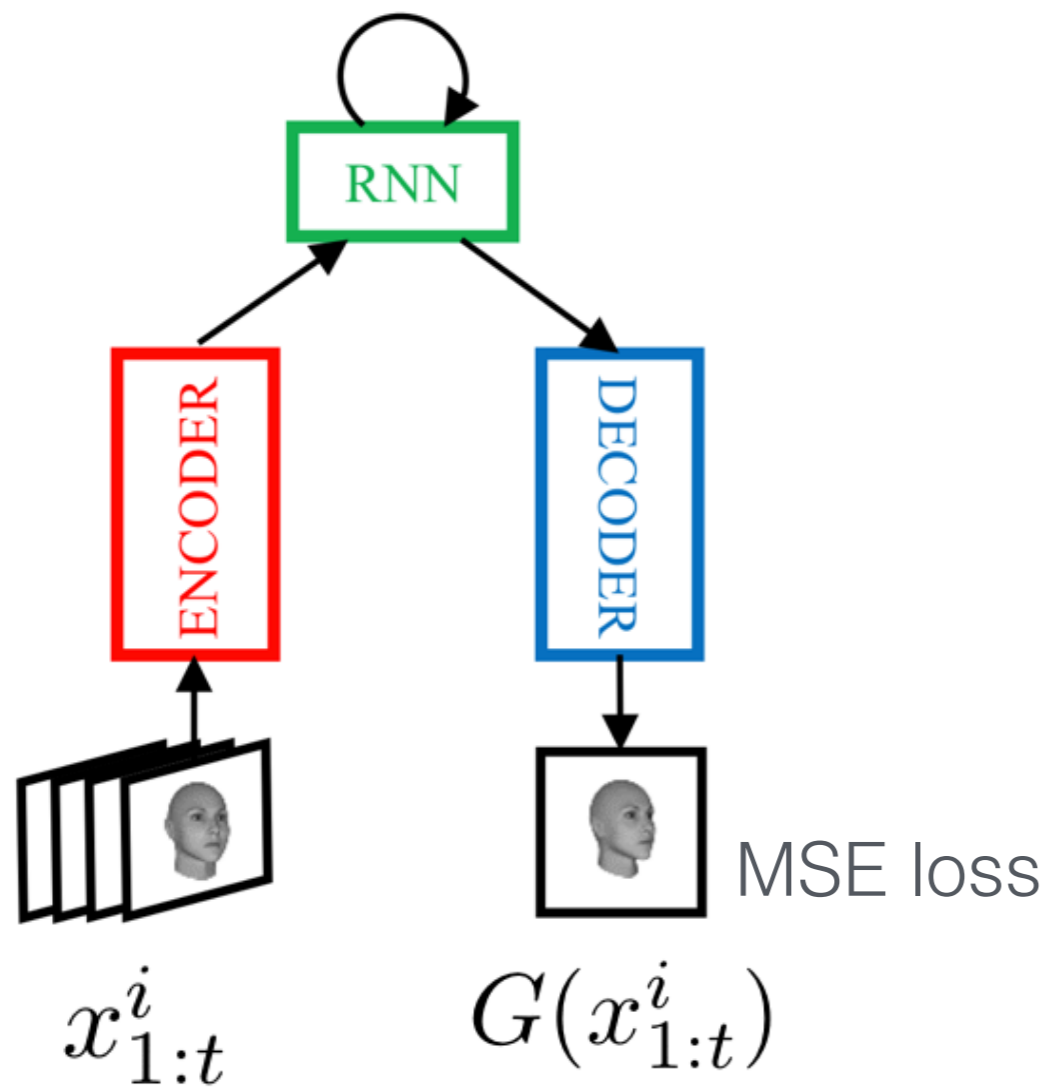
Truth

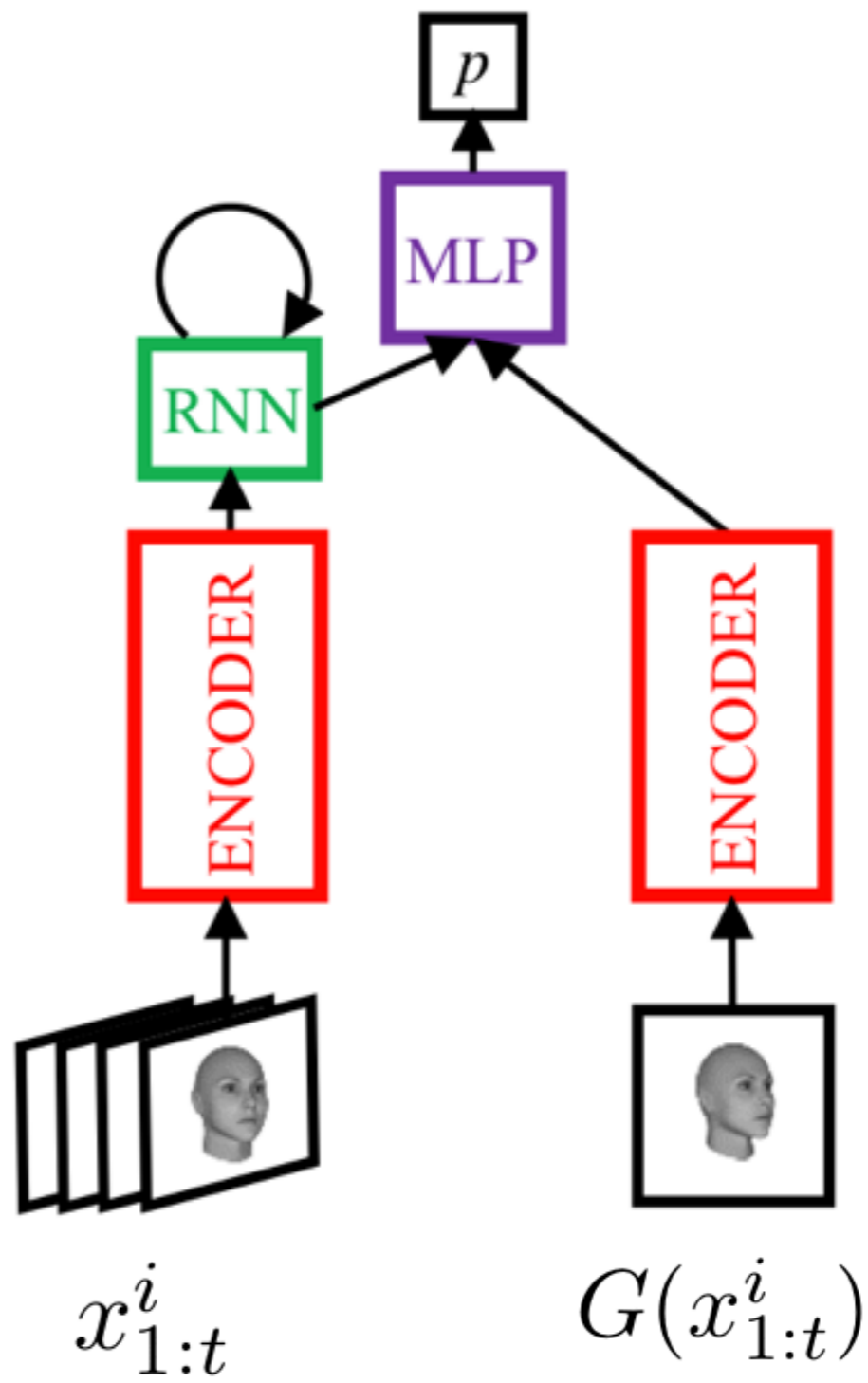
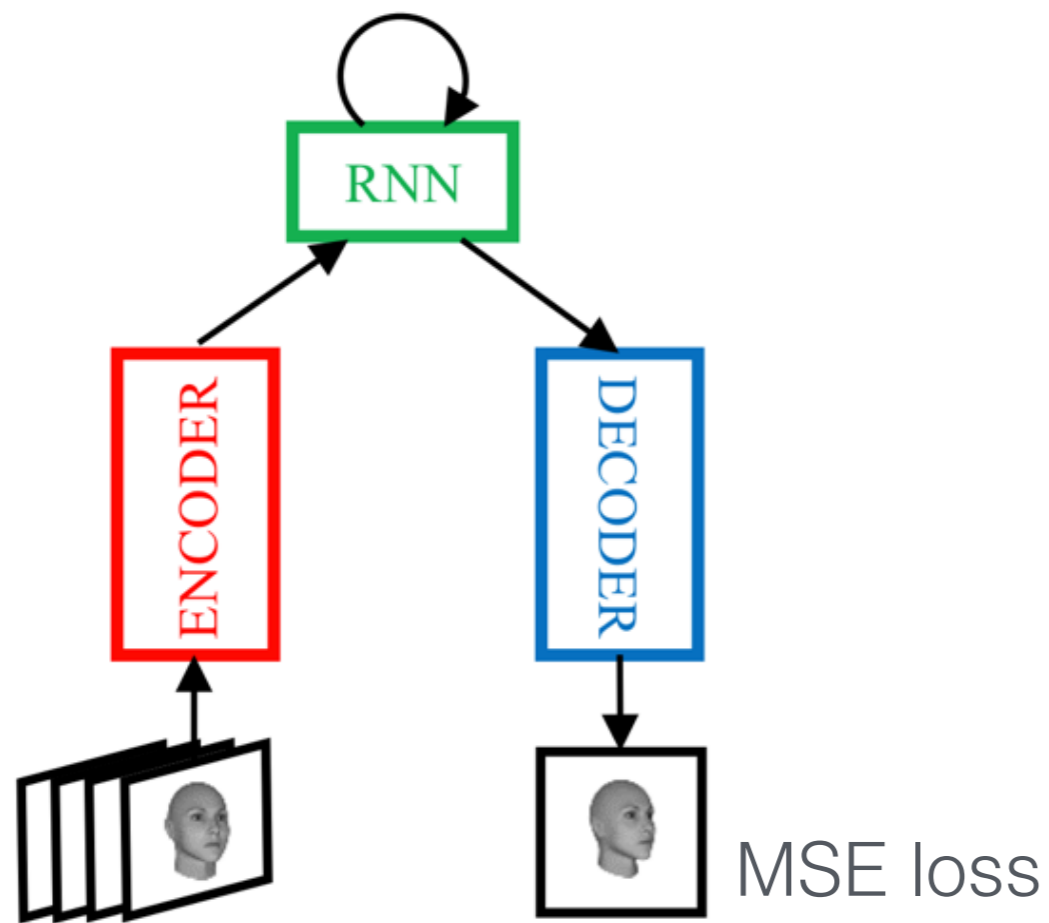


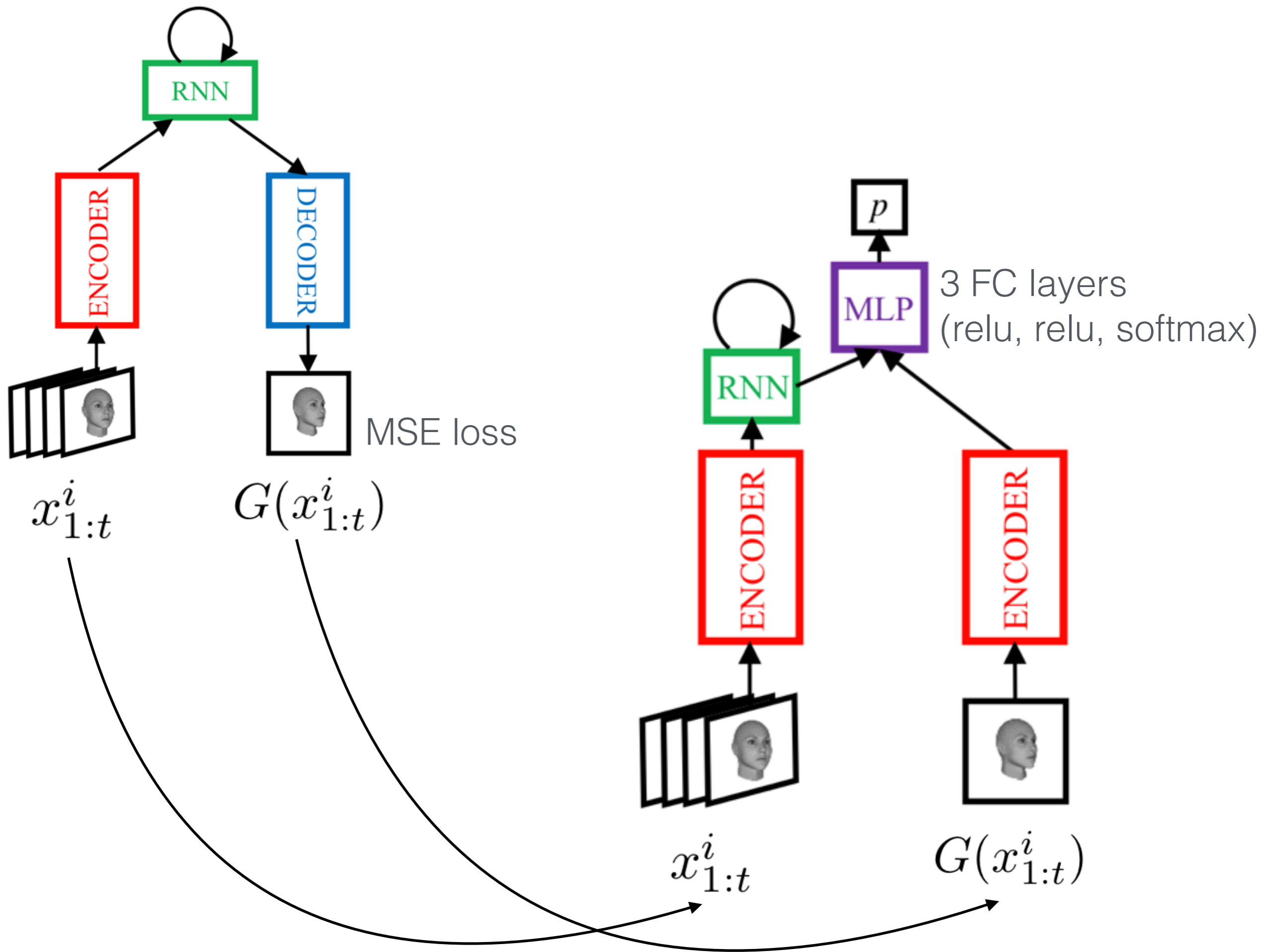


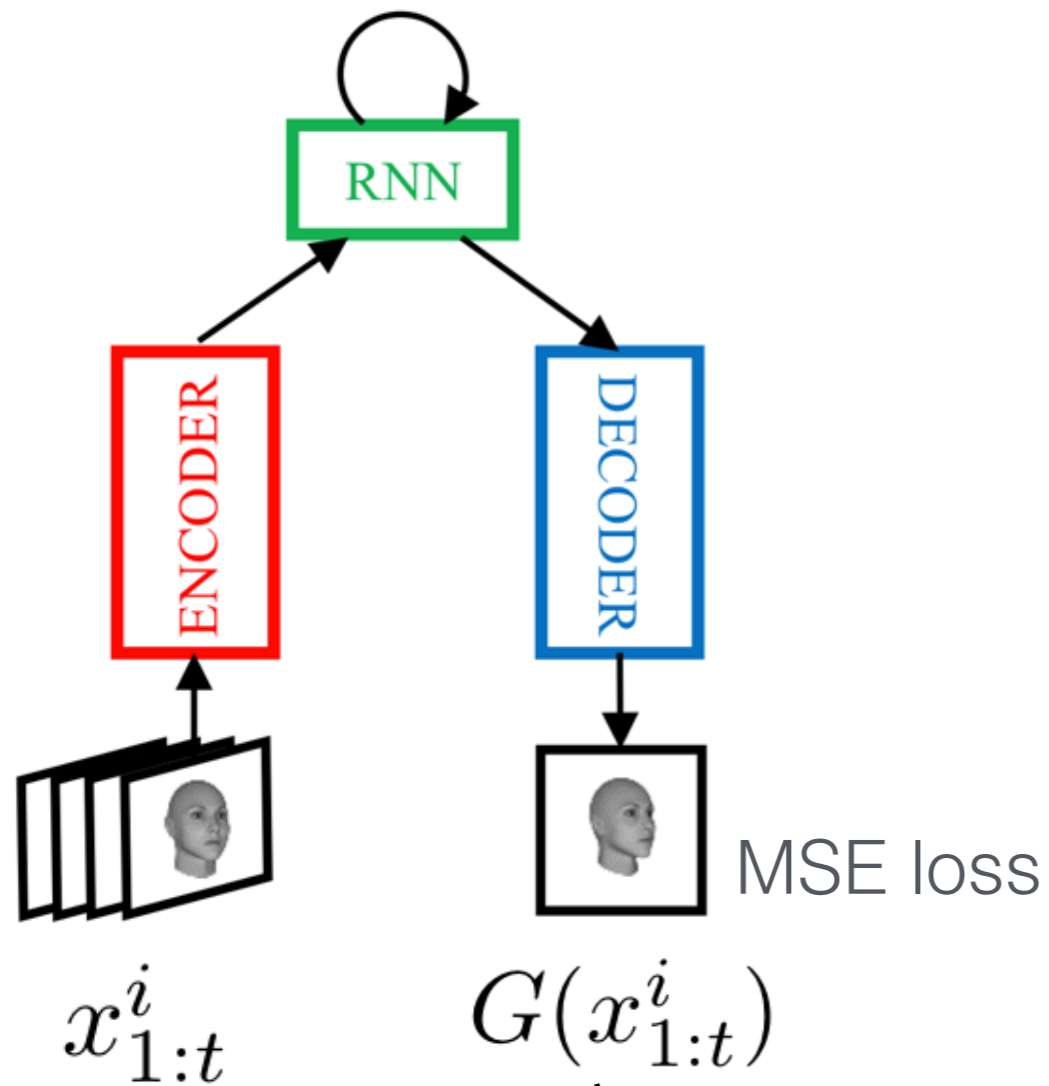




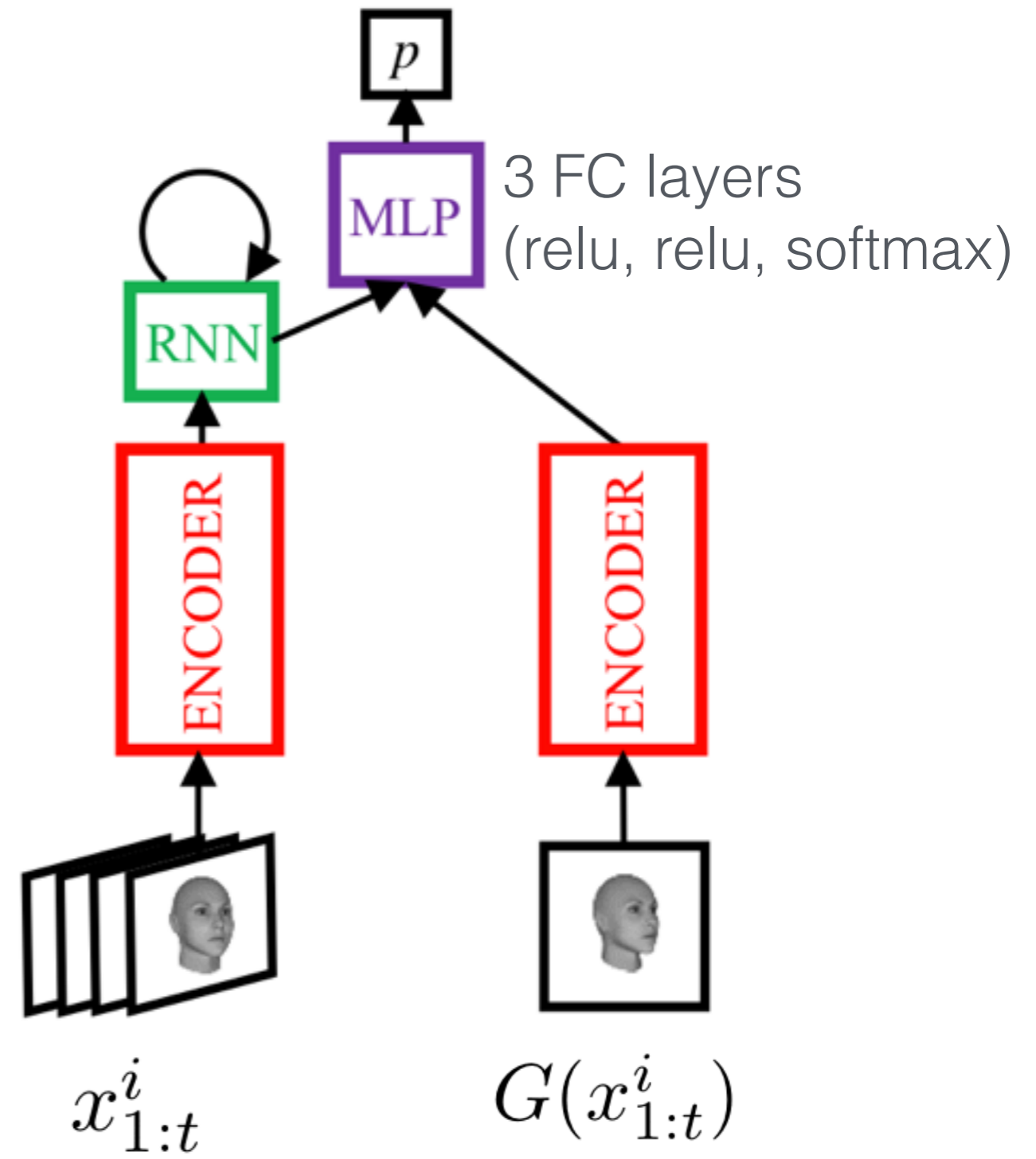




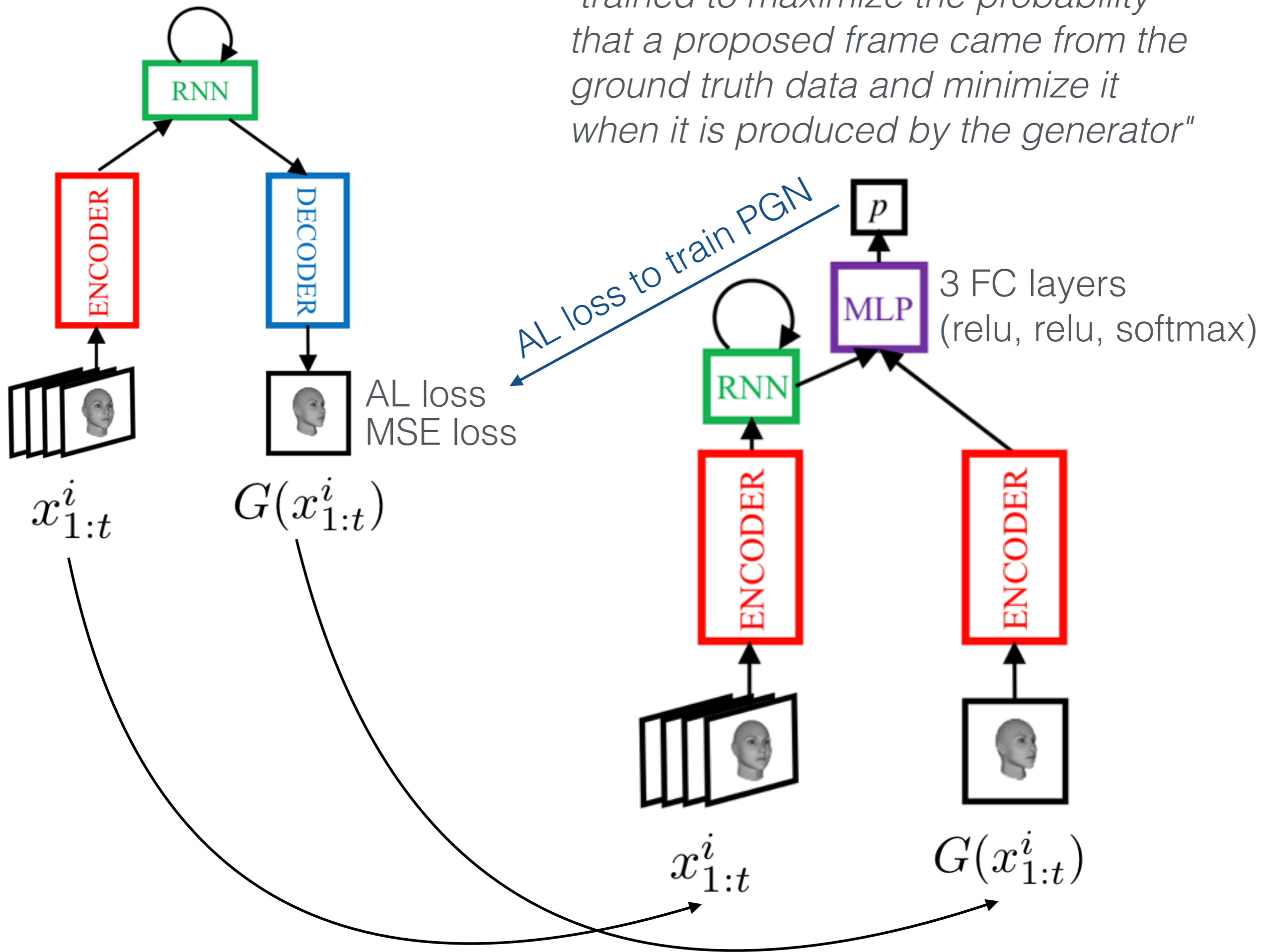




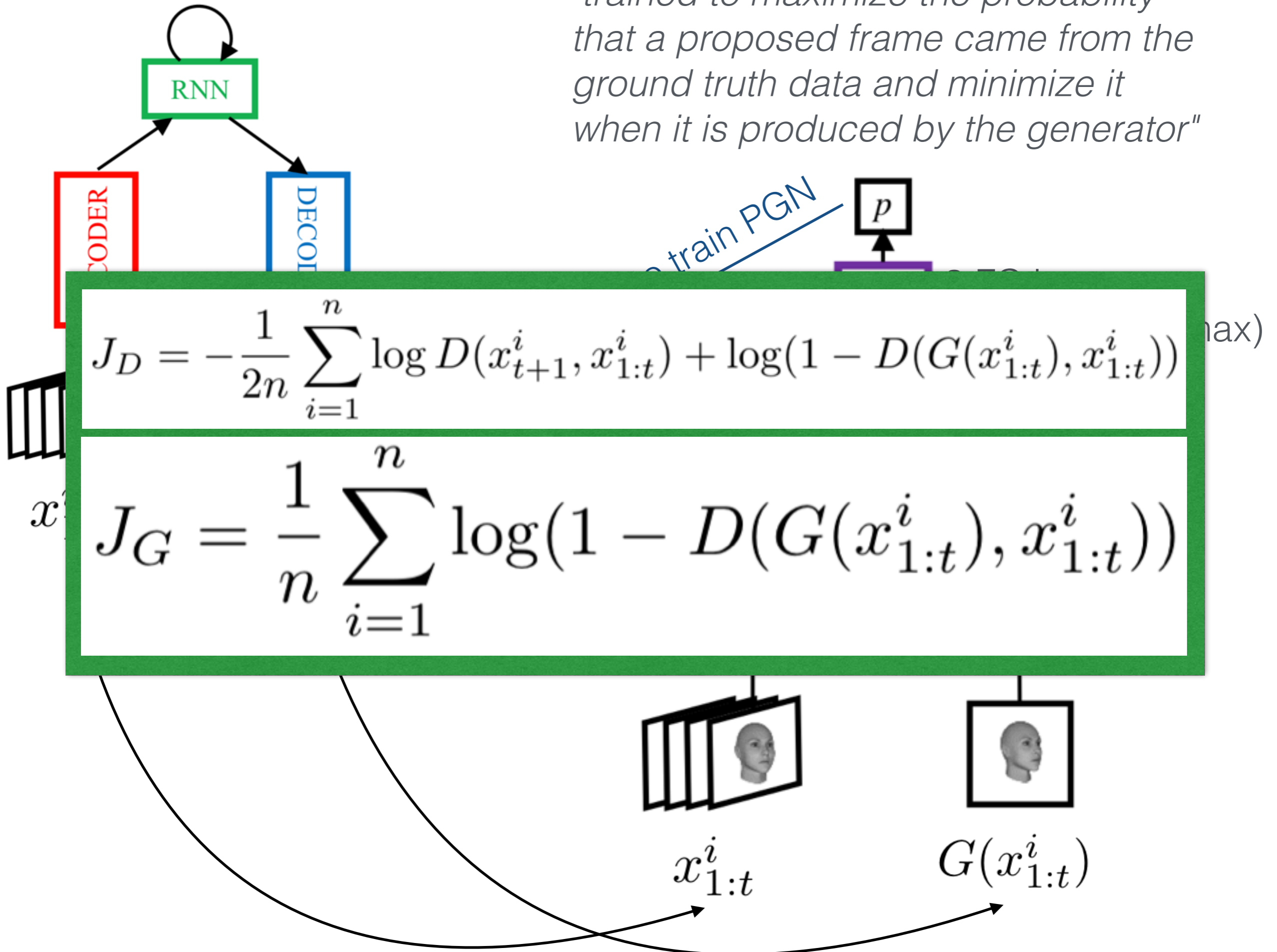
"trained to maximize the probability that a proposed frame came from the ground truth data and minimize it when it is produced by the generator"

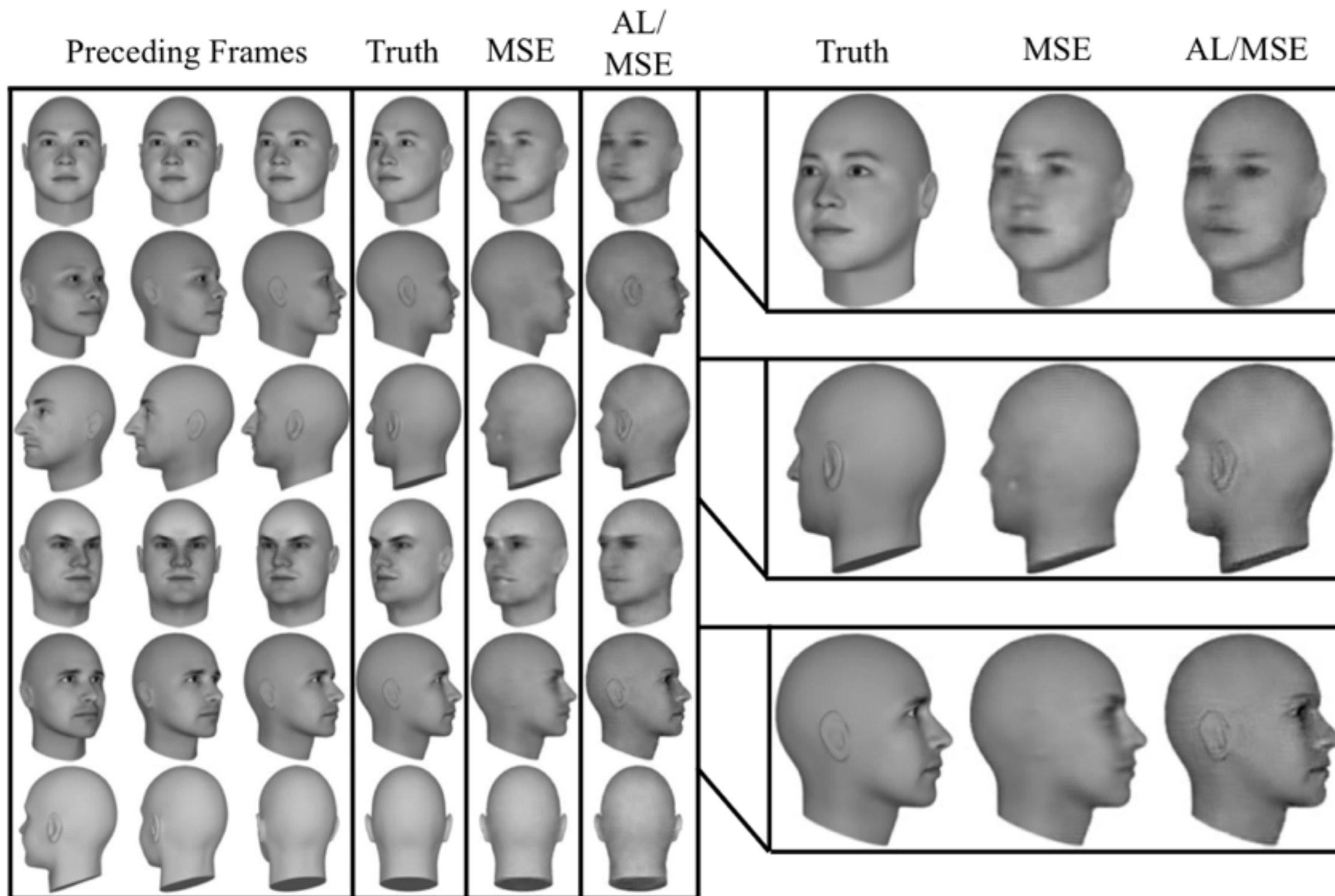


"trained to maximize the probability that a proposed frame came from the ground truth data and minimize it when it is produced by the generator"



"trained to maximize the probability that a proposed frame came from the ground truth data and minimize it when it is produced by the generator"





“with adversarial loss alone the generator easily found solutions that fooled the discriminator, but did not look anything like the correct samples”

MSE model is fairly faithful to the identities of the faces, but produces blurred versions

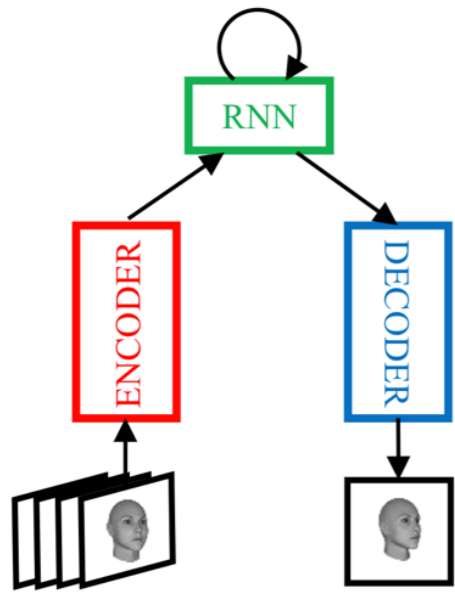
combined AL/MSE model tends to underfit the identity towards a more average face



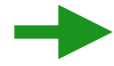
PART III

INTERNAL REPRESENTATIONS AND LATENT VARIABLES

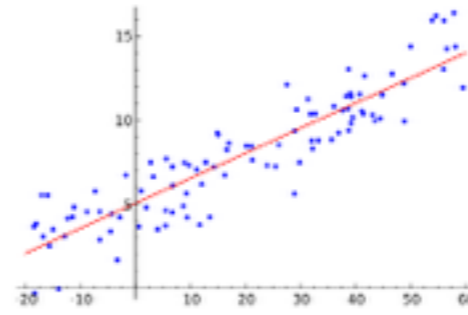
"we are interested in understanding the representations learned by the models"



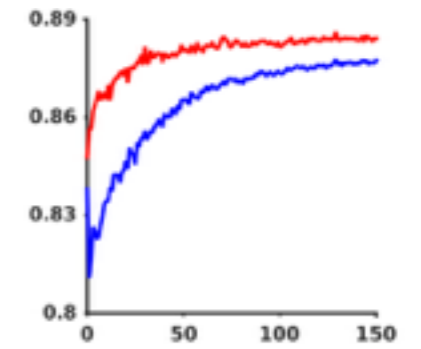
PGN model



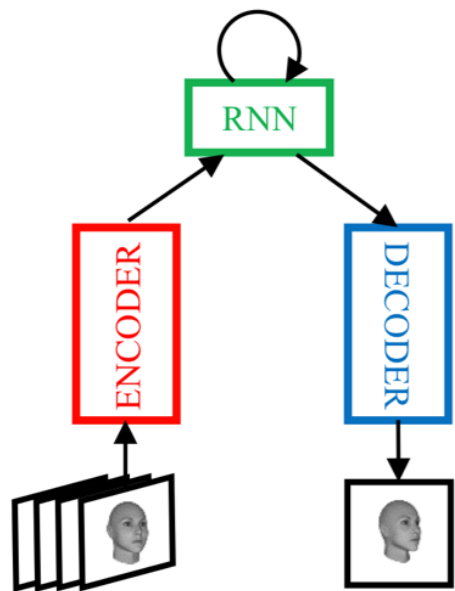
LSTM activities



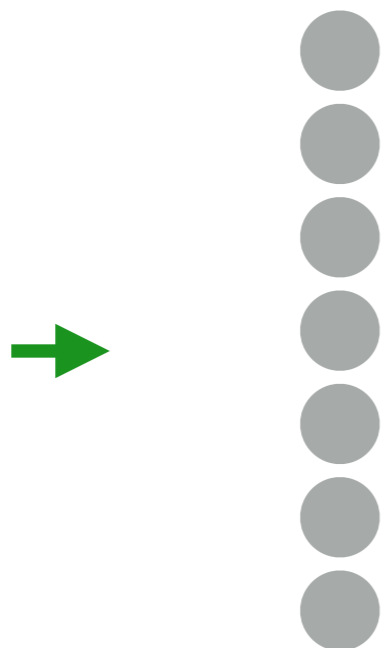
L2 regression



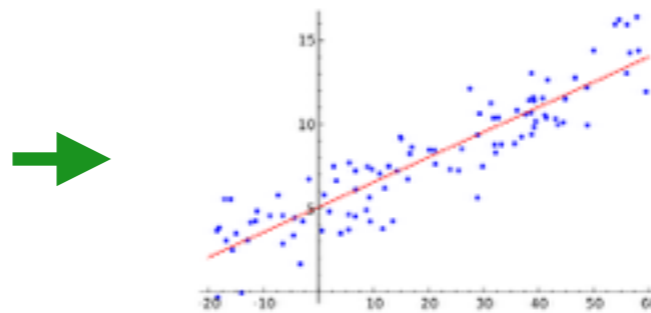
Value of a latent variable



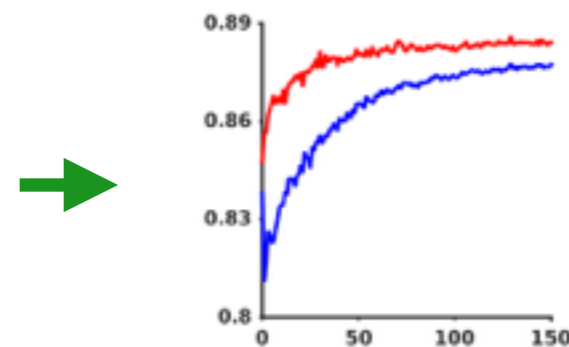
PGN model



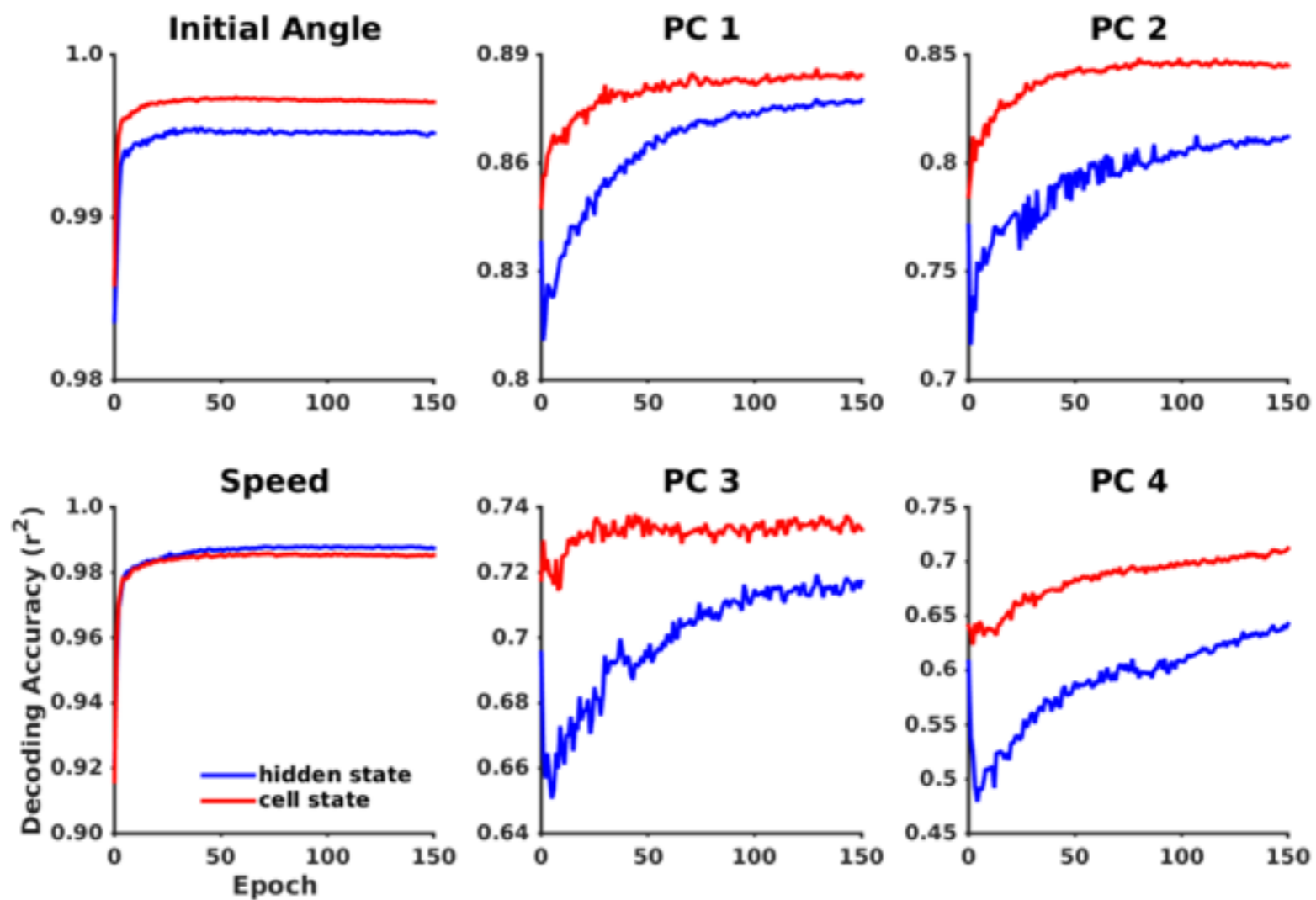
LSTM activities



L2 regression



Value of a latent variable



MULTIDIMENSIONAL SCALING

“An MDS algorithm aims to place each object in N-dimensional space such that the between-object distances are preserved as well as possible.”

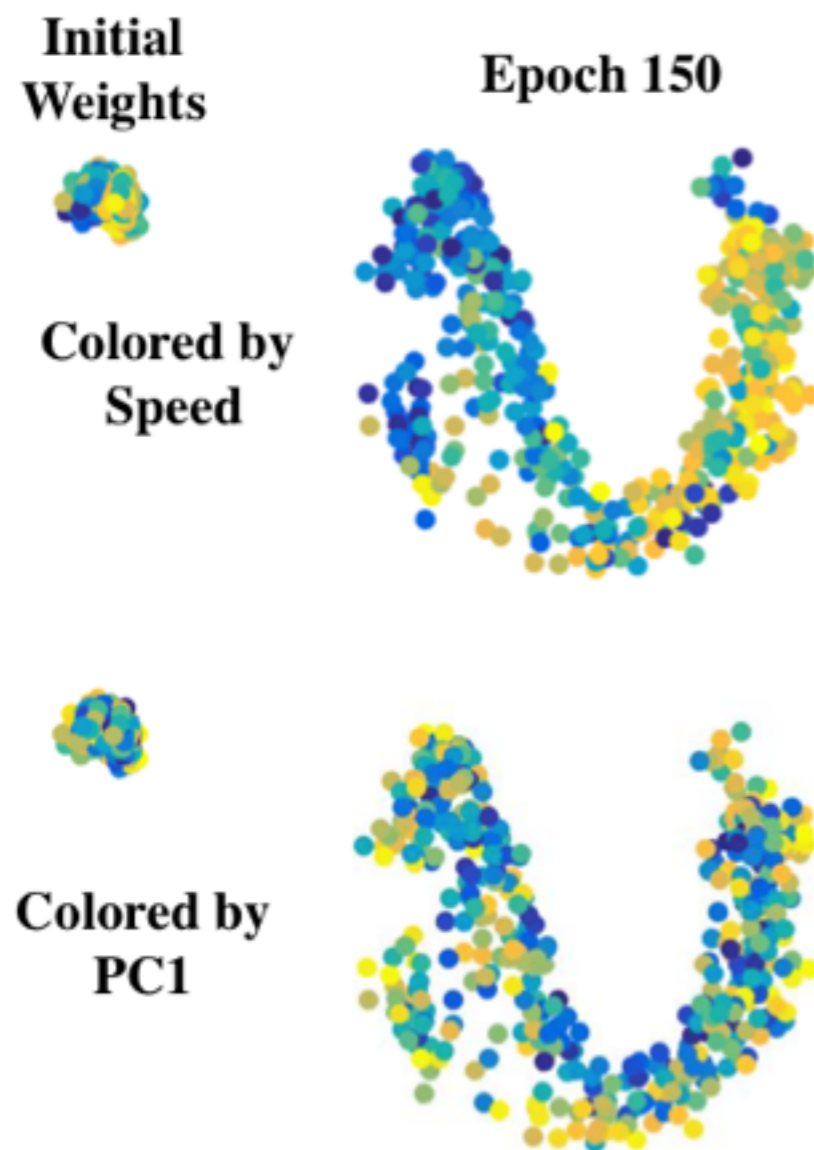


Figure 5: MDS of LSTM Space

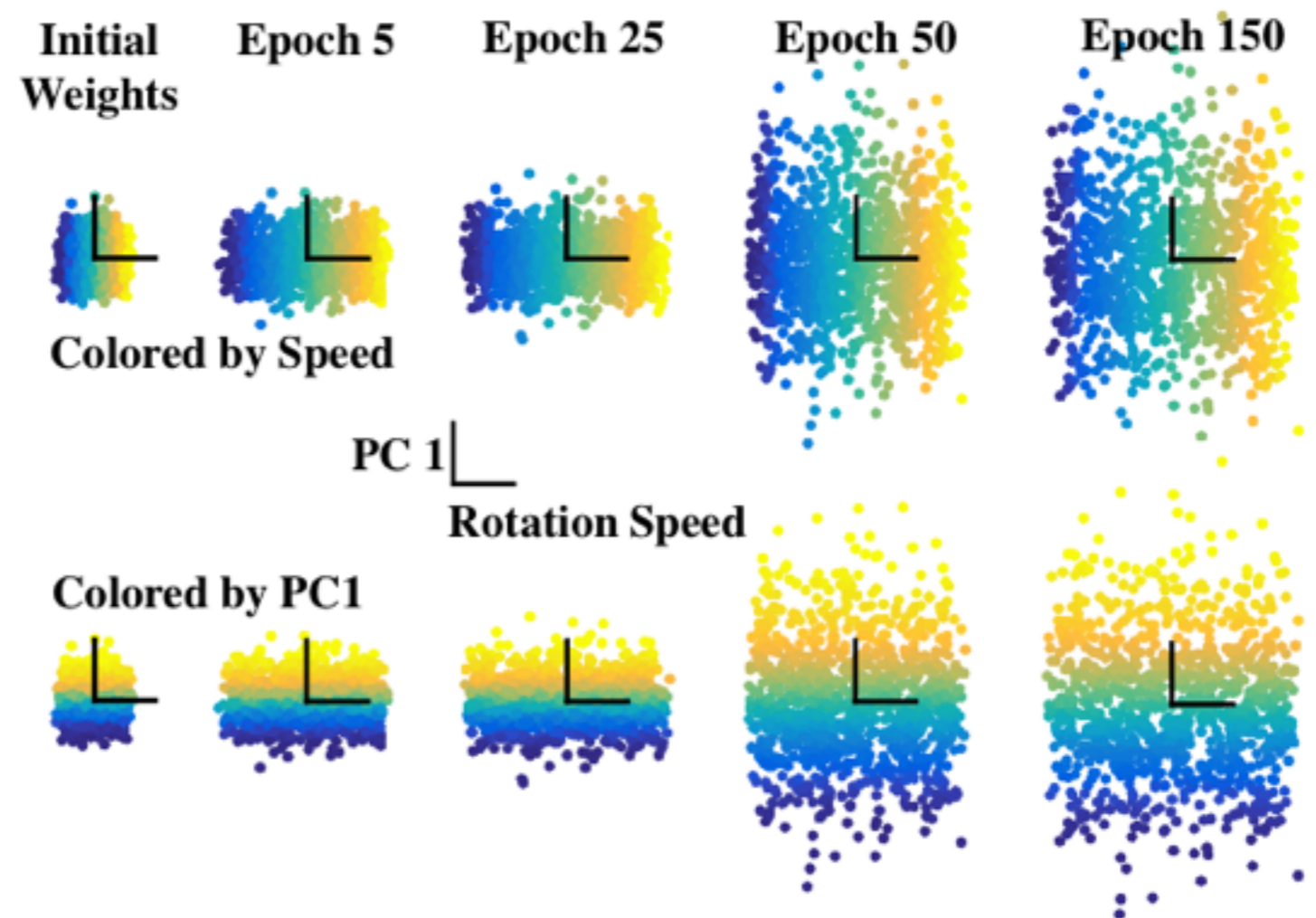
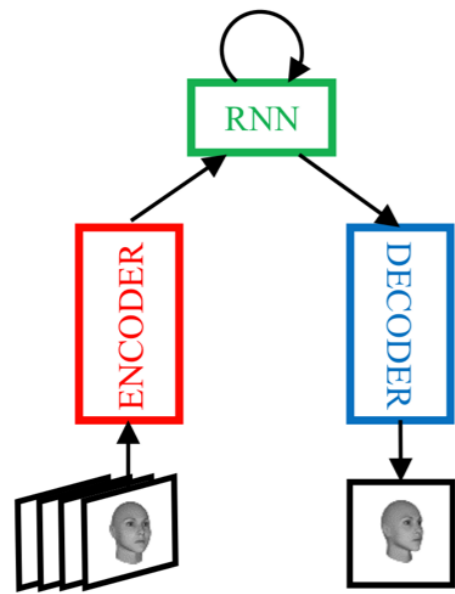


Figure 6: Projection of LSTM feature space on latent variables axes. Axes are in the direction of regression coefficients. A different regression was fit for each epoch.

*"representations trained with
a predictive loss outperform
other models of comparable
complexity in a supervised
classification problem"*

PART IV
USEFULNESS OF PREDICTIVE LEARNING

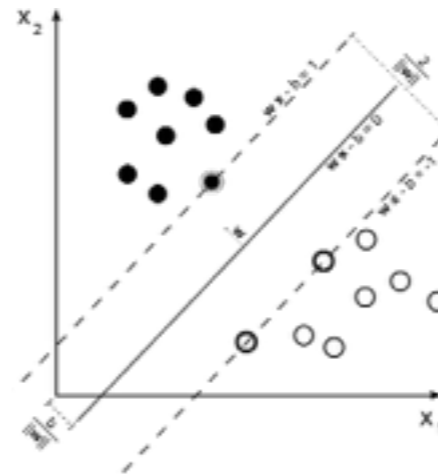
THE TASK: 50 randomly generated faces (12 angles per each)



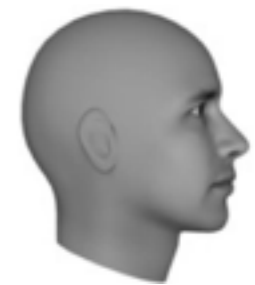
Generative models:



Internal representation

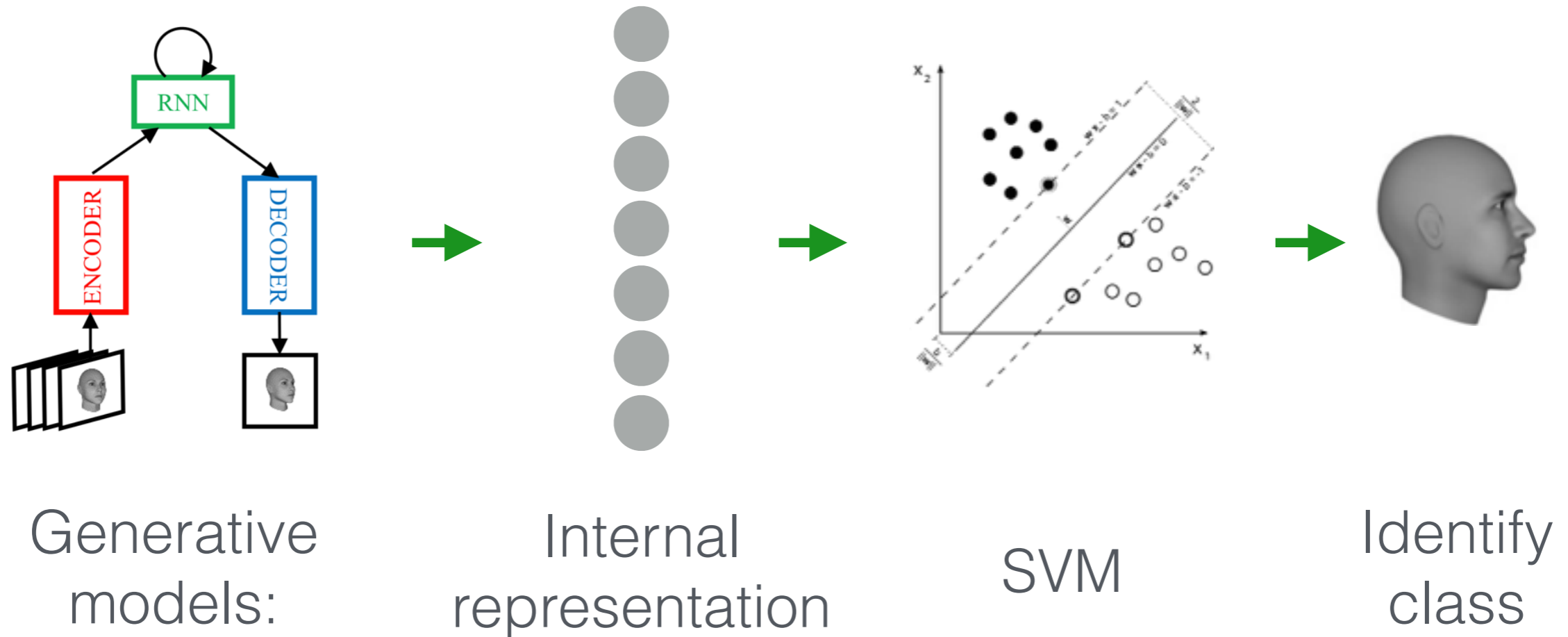


SVM



Identify class

THE TASK: 50 randomly generated faces (12 angles per each)



- Encoder-LSTM-Decoder to predict **next** frame (PGN)
- Encoder-LSTM-Decoder to predict **last** frame (AE LSTM dynamic)
- Encoder-LSTM-Decoder on frames made into **static** movies (AE LSTM static)
- Encoder-FC-Decoder with **#weights** as in LSTM (AE FC #weights)
- Encoder-FC-Decoder with **#units** as in LSTM (AE FC #units)

